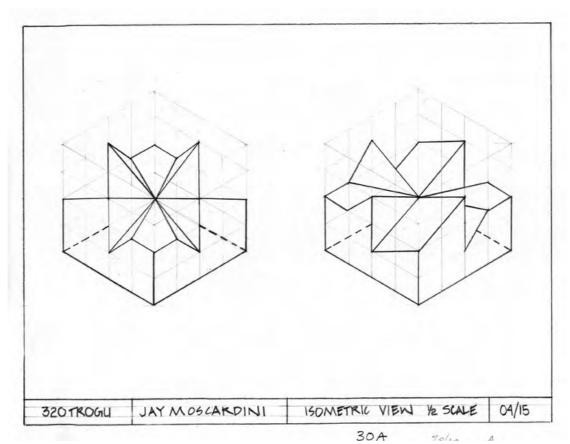
ROTATIONAL GEOMETRY AS A TEACHING TOOL: APPLYING THE WORK OF GIORGIO SCARPA

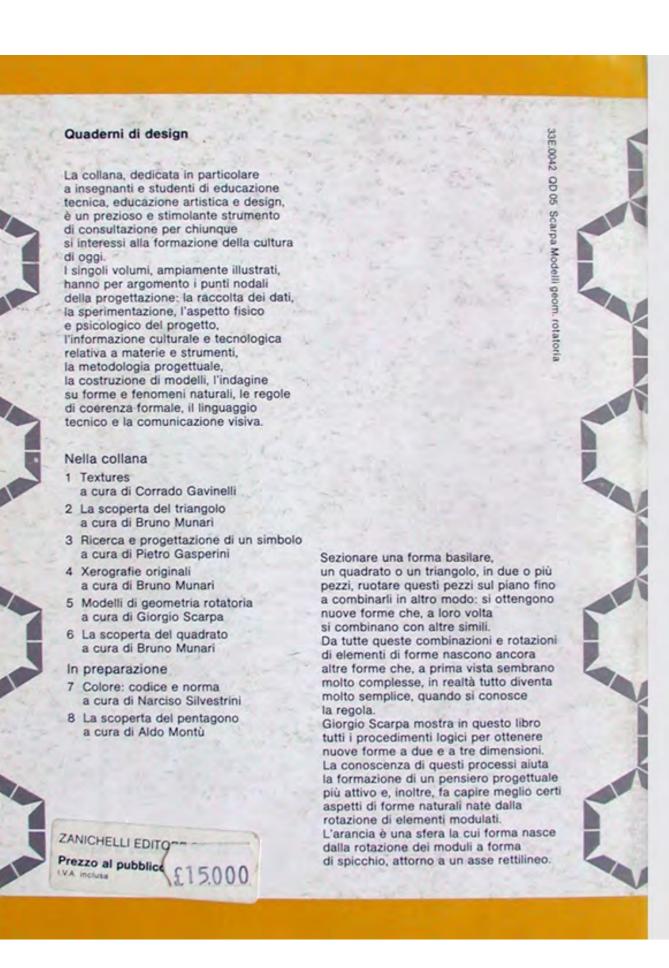
PINO TROGU – SAN FRANCISCO STATE UNIVERSITY

SIXTH INTERNATIONAL CONFERENCE ON DESIGN PRINCIPLES AND PRACTICES

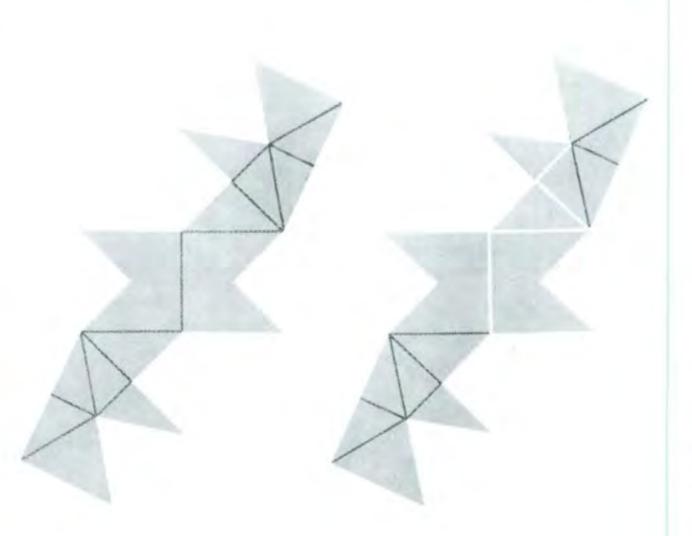
LOS ANGELES, JANUARY 21, 2012



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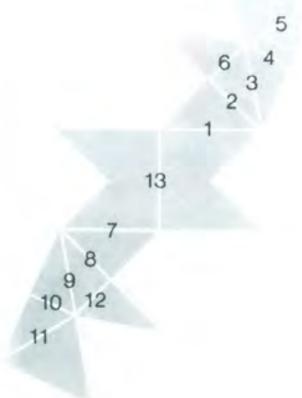




I collegamenti degli sviluppi di superficie esterna coi piani interni dell'esaedro determinano, come abbiamo visto, nuove configurazioni, nuovi sviluppi, ripiegando i quali, e passando quindi dal piano allo spazio, si ottengono moduli tridimensionali. Il passaggio da due dimensioni a tre dipende:

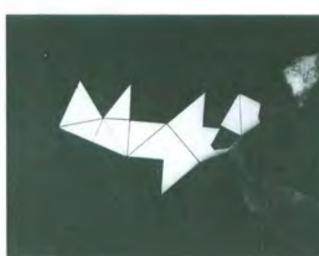
 dal far assumere la funzione di assi di rotazione a linee che dimensionano le superfici degli sviluppi;

- dall'individuare lungo queste configurazioni lineari, sequenze di piegatura costituenti determinati percorsi;
- dalla scelta dei percorsi più logici ed economici;
- dal ruotare (piegare) secondo determinati angoli, parti del modello intorno a queste linee (assi);
- dal regolare numero e tipo di operazioni in riferimento a schemi di organizzazione formale.





Esempi: ordine di piegatura indicato sulle linee interne dai numeri 1-13, relativo alla definizione del modulo;



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9. metà diagonale interna











5. metà diagonale interna

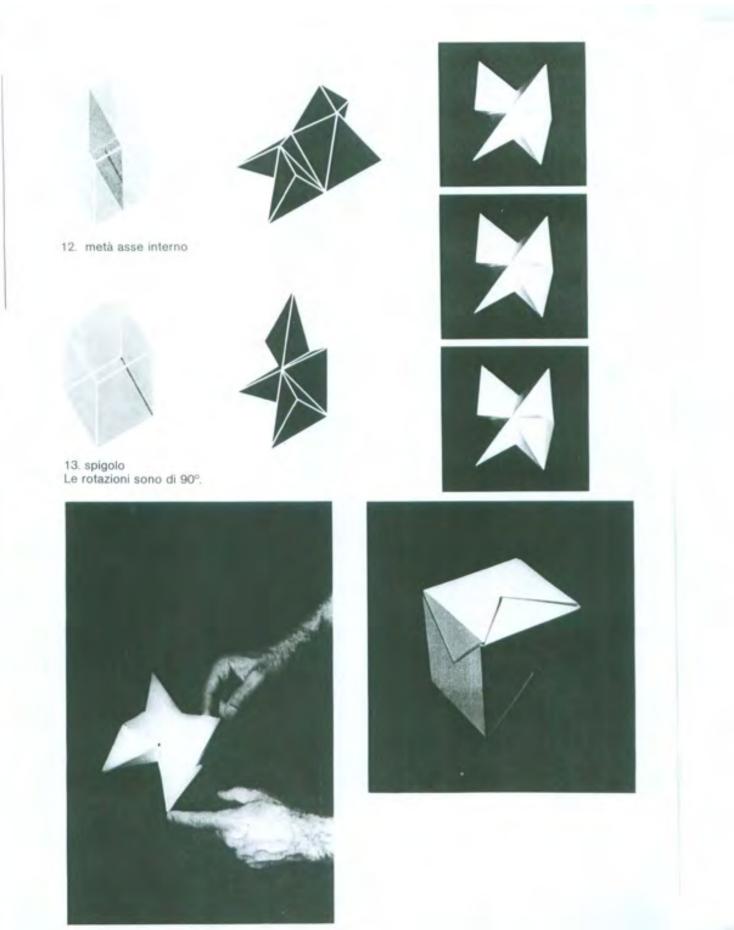
8. metà diagonale di una faccia

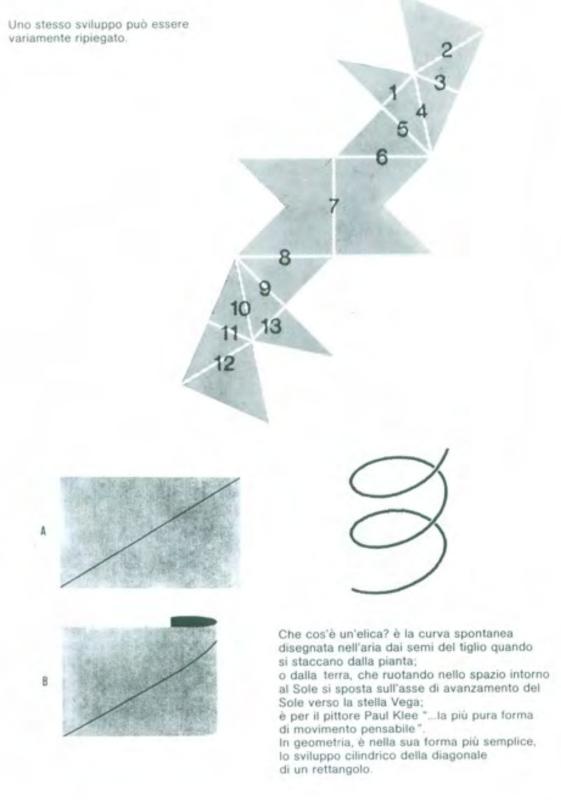
11. metà diagonale interna

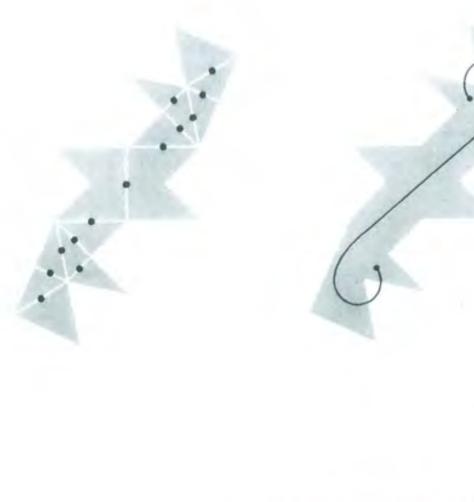
38

2. metà diagonale di una faccia

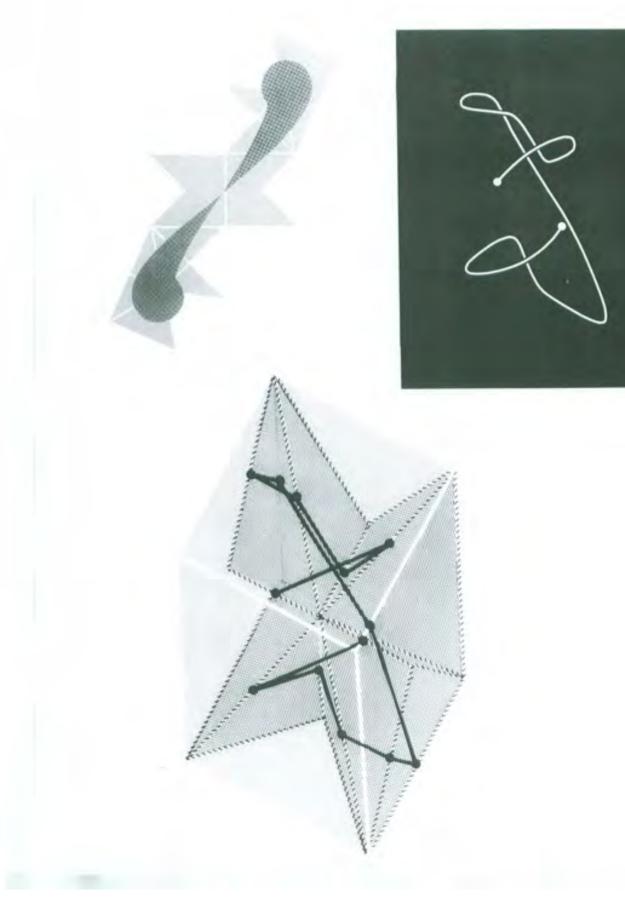
1. spigolo del cubo

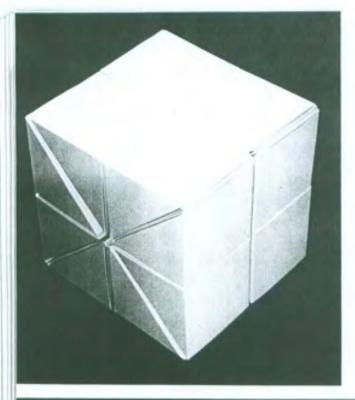




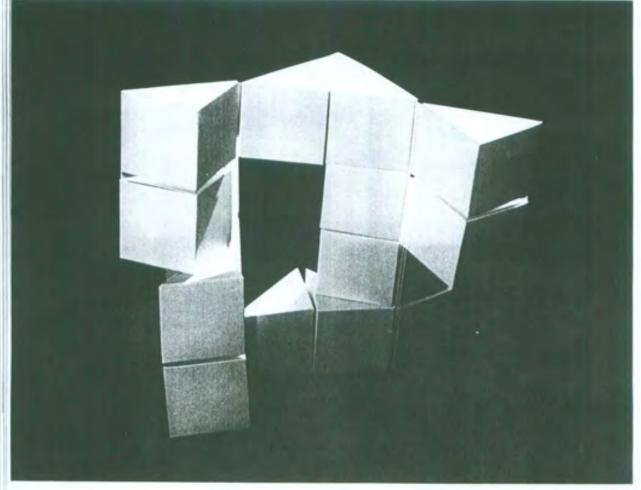


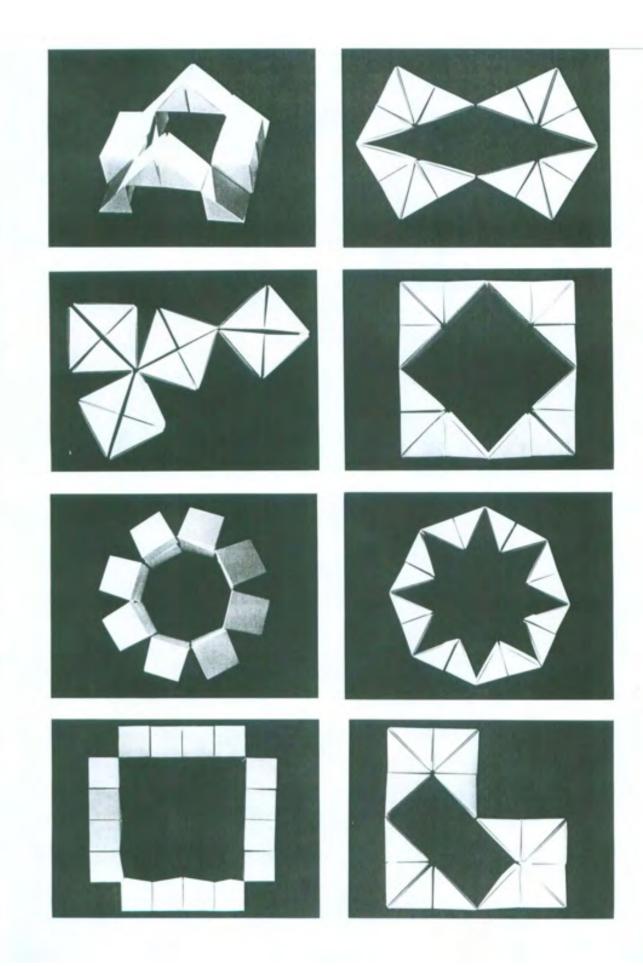
Consideriamo i piani articolati in due raggruppamenti (1-7 e 7-13, v. pagine precedenti) intorno al centro di rotazione 7; la loro forma complessiva è simile ad una esse che risulta più visibile se con una linea curva raccordiamo tra loro i punti da 1 a 13, o disegnamo due regioni che delimitano il tracciato puntiforme, accentuando l'andamento ciclico a due bracci dello sviluppo. La composizione dei movimenti di piegatura con cui portiamo nello spazio i piani, ruotandoli intorno agli assi 1-13, dà come risultante una traiettoria a forma di elica. Con questa mappa spaziale che unifica la successione dei movimenti, definiamo lo sviluppo in terza dimensione. La rappresentazione di mappe dei movimenti di ripiegamento deve avere come fine il controllo dell'intero processo, in vista della sua semplificazione.



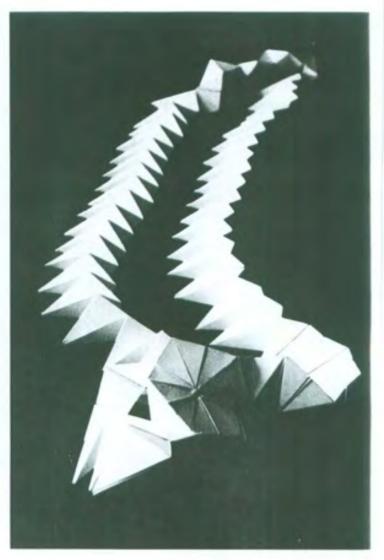


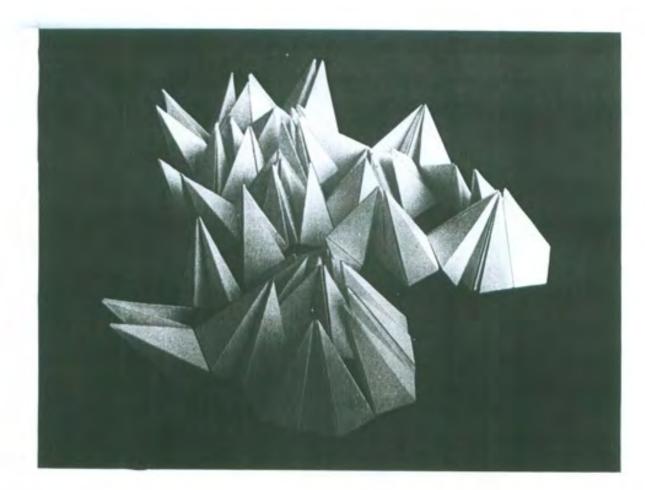
Rotazioni di catene esaedriche.













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TWIN SECTION

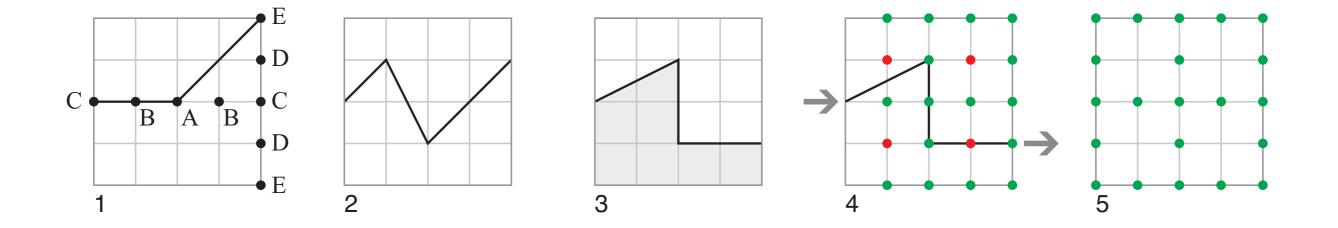


Fig. 1

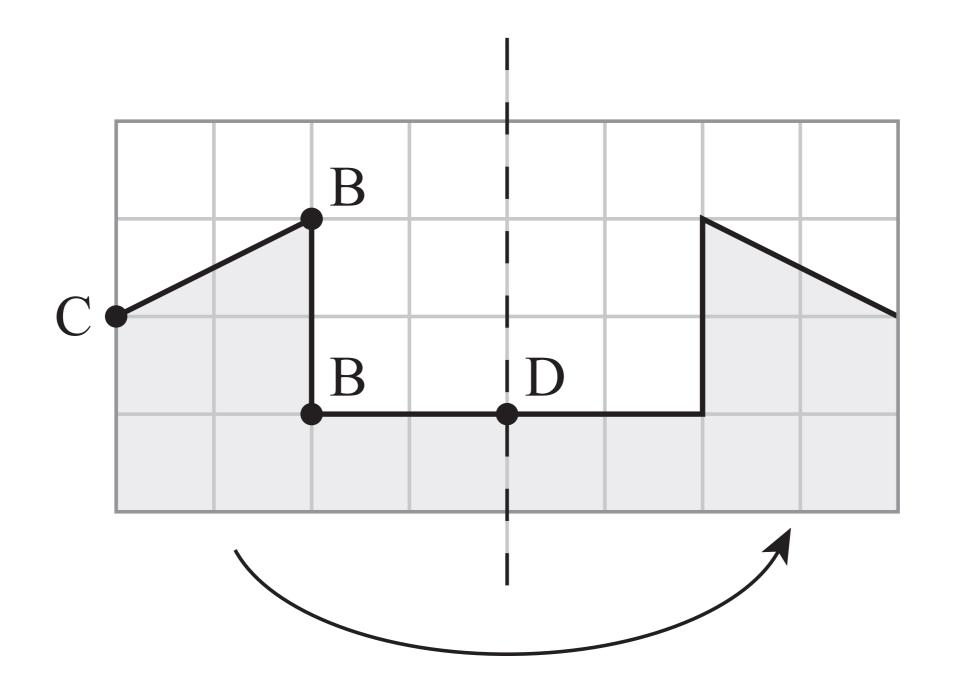


Fig. 2

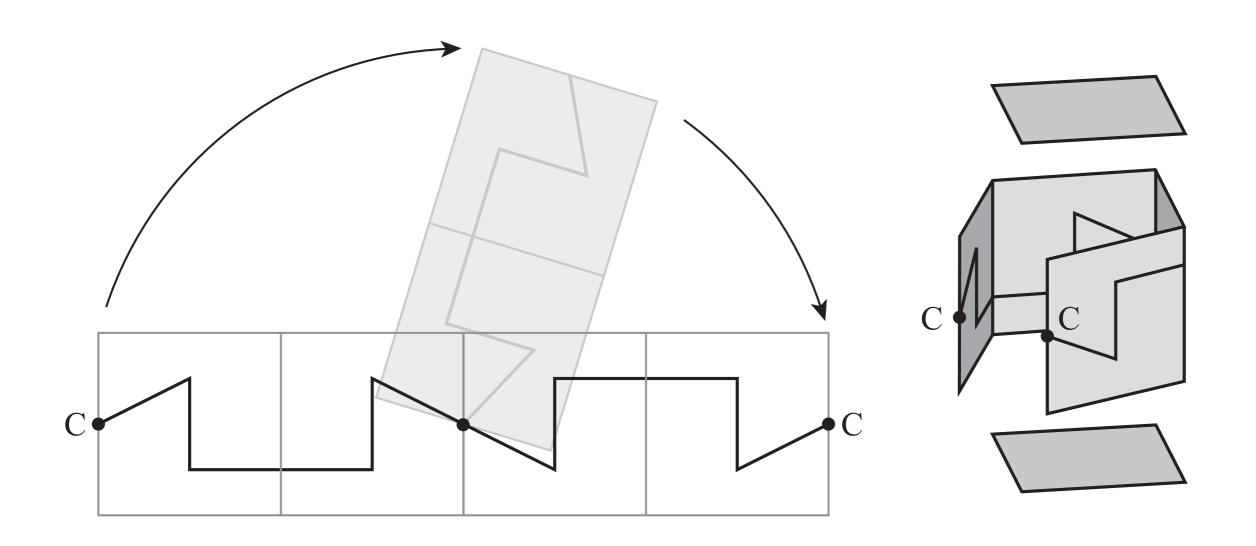


Fig. 3

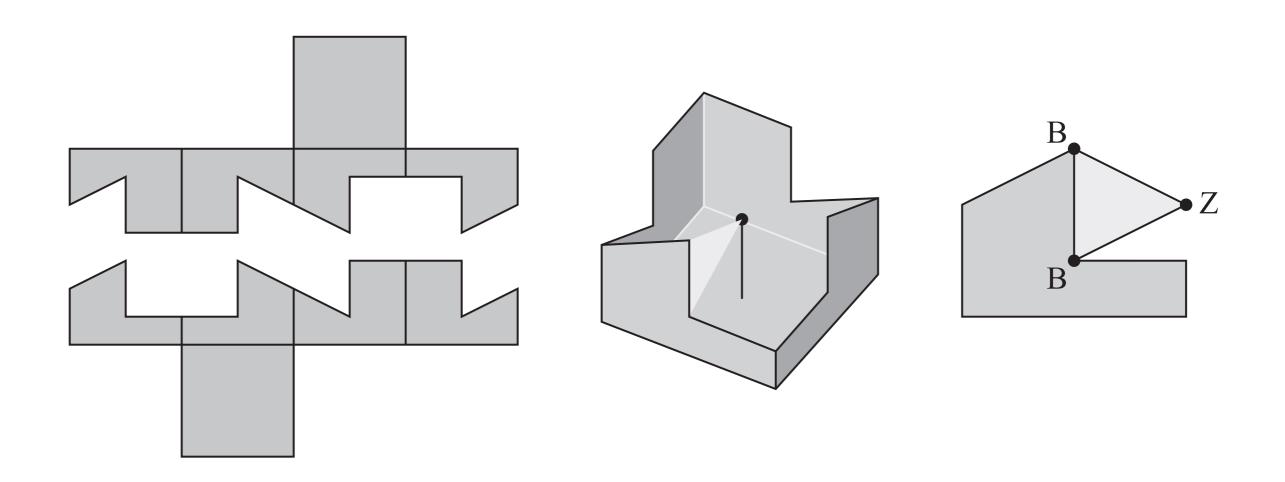


Fig. 4

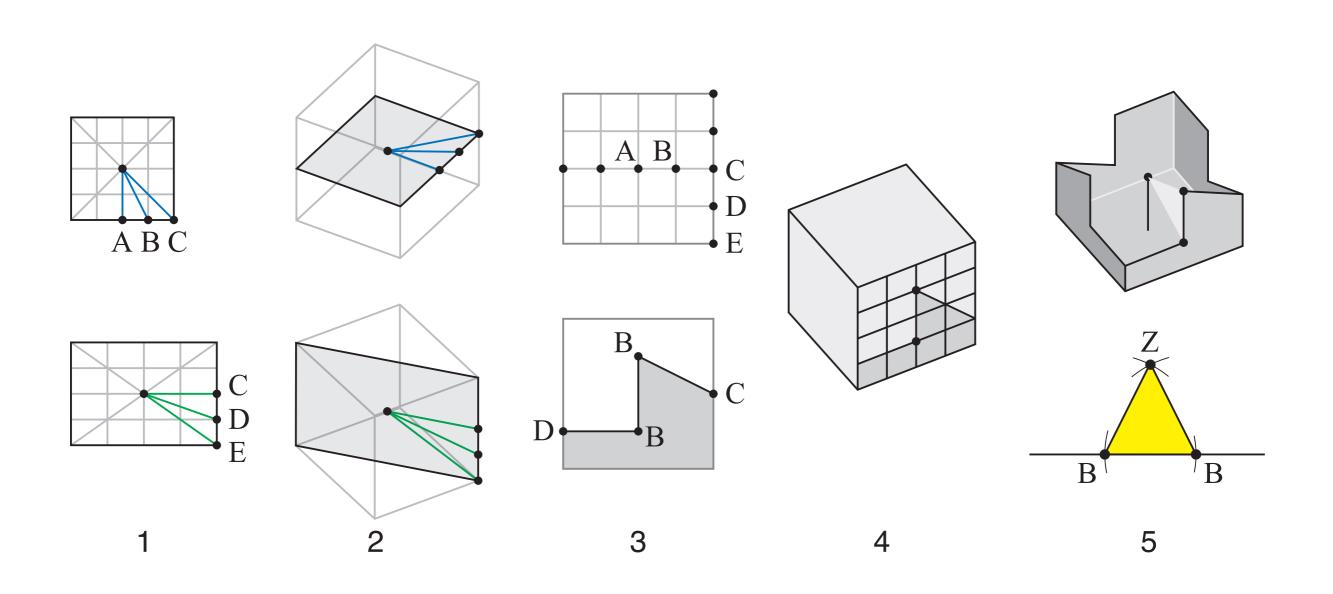
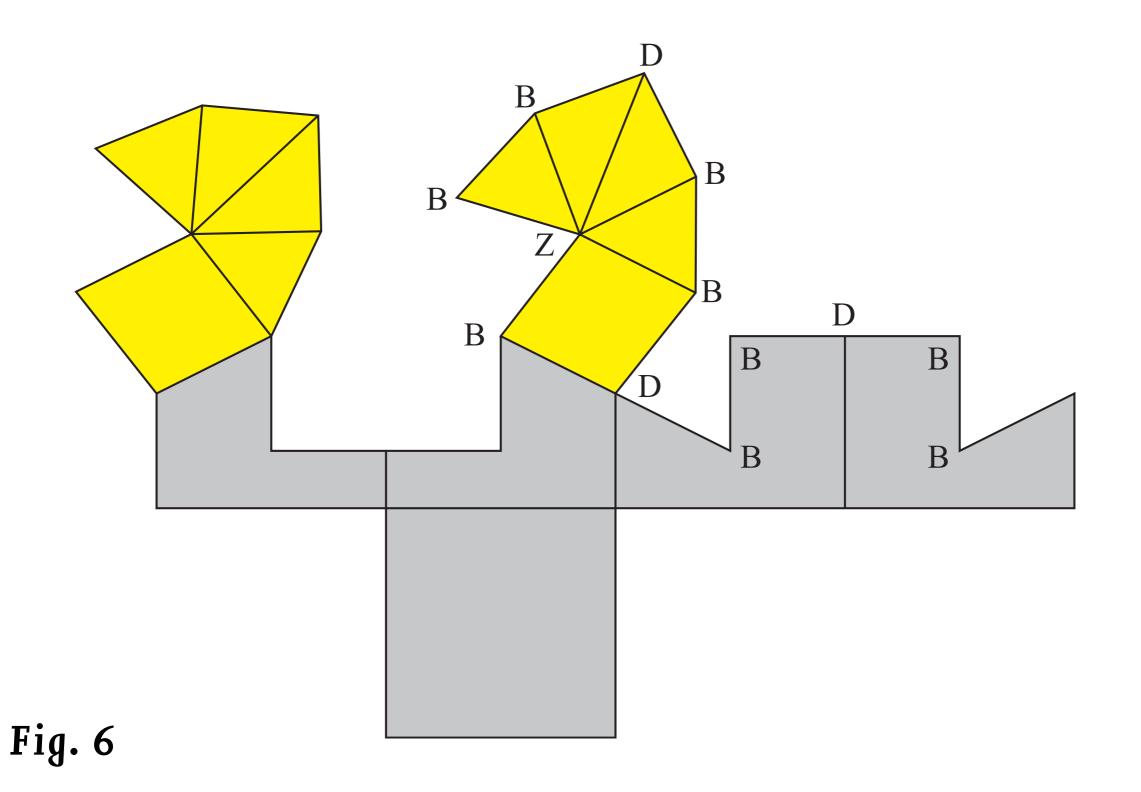


Fig. 5



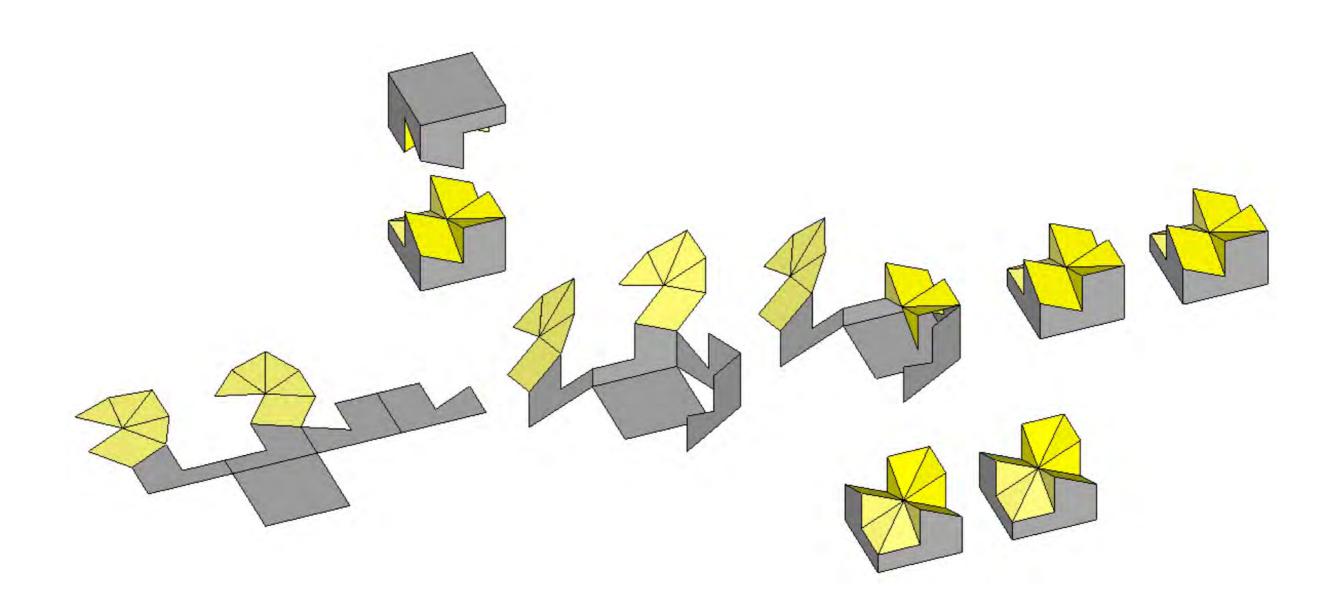


Fig. 7

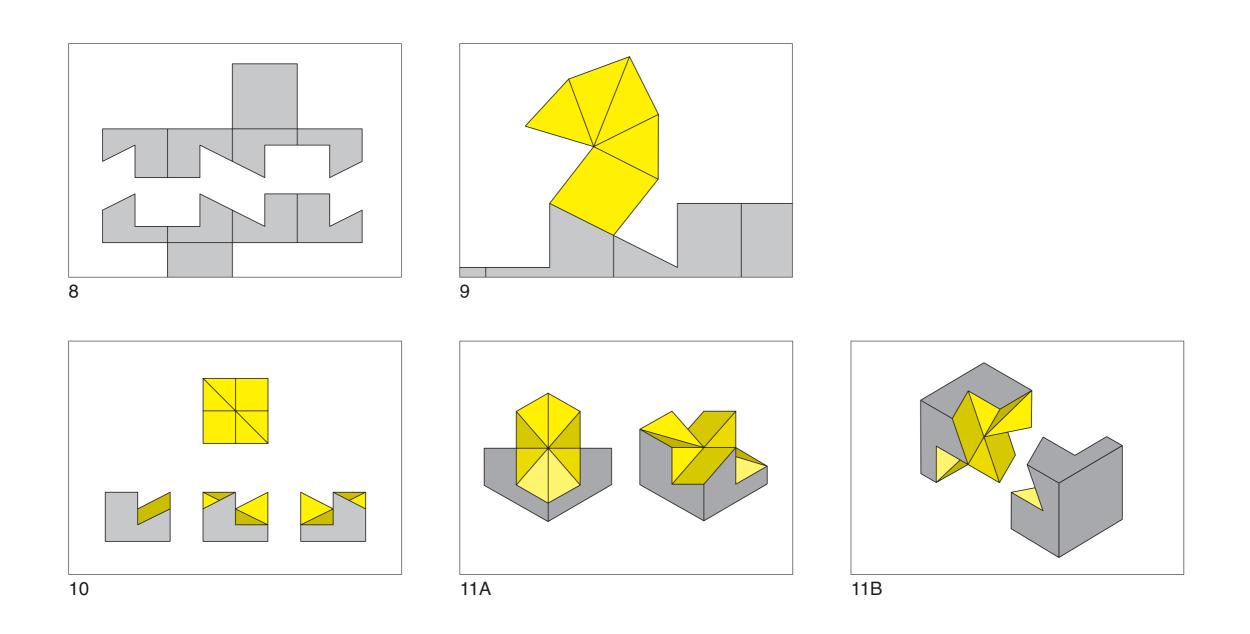
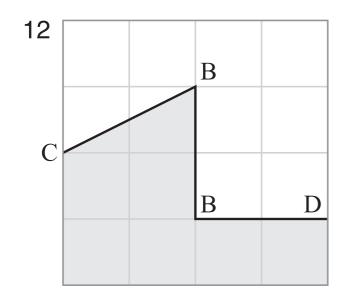


Fig. 8-11

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TRIPLET SECTION



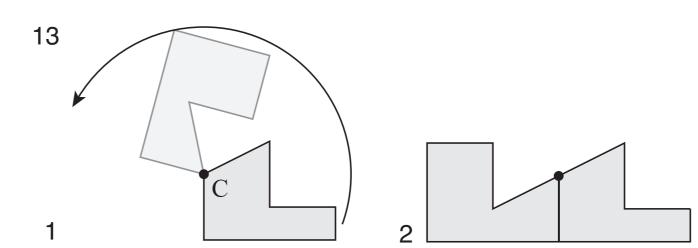


Fig. 12-13

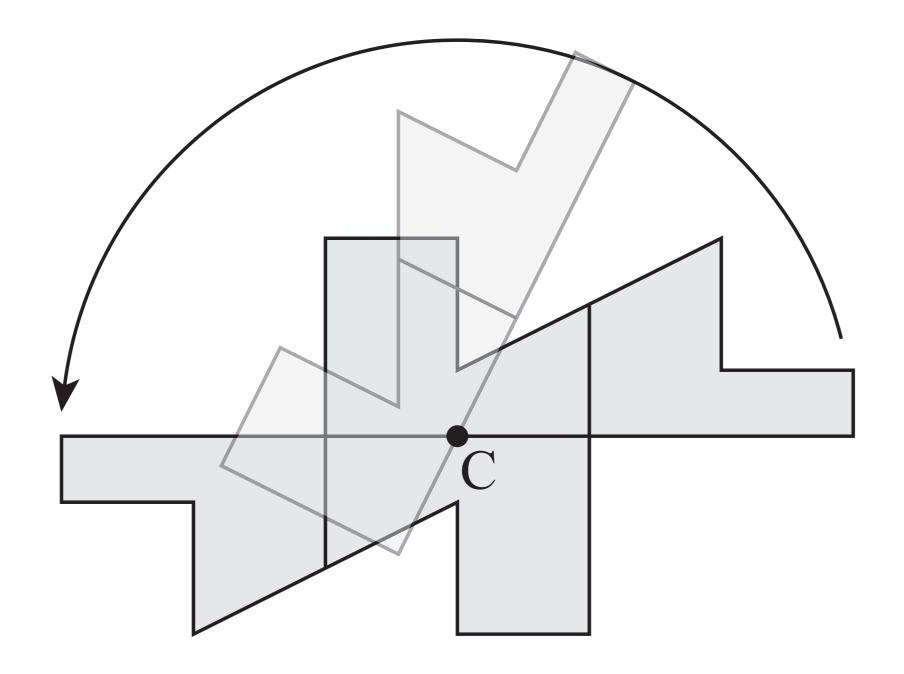


Fig. 14

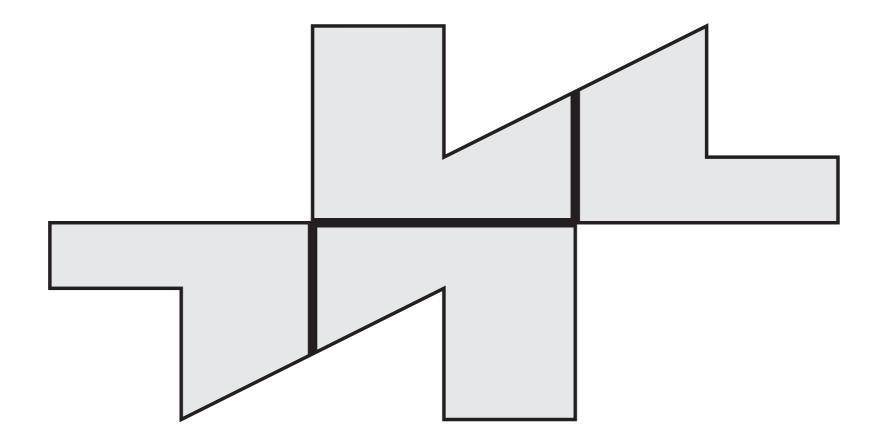


Fig. 15

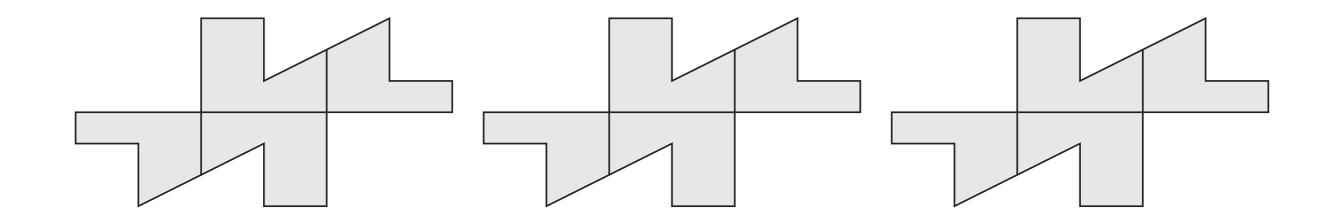


Fig. 16

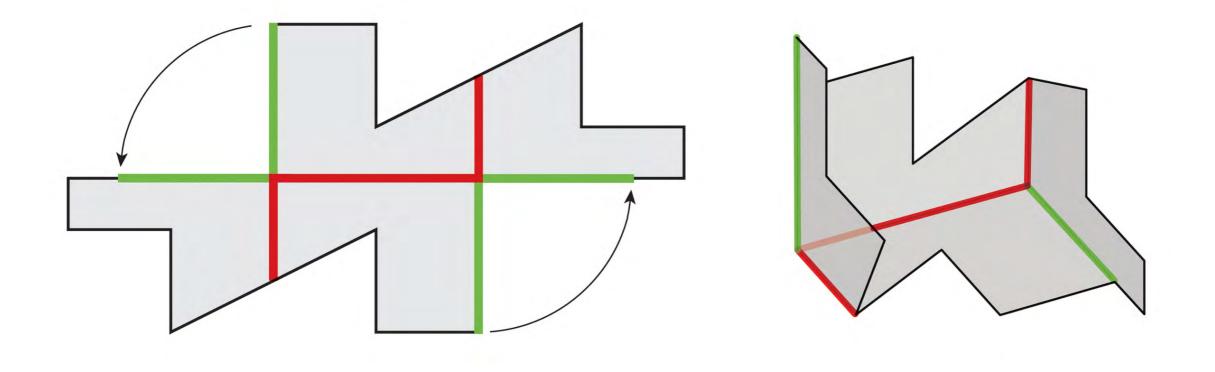


Fig. 17

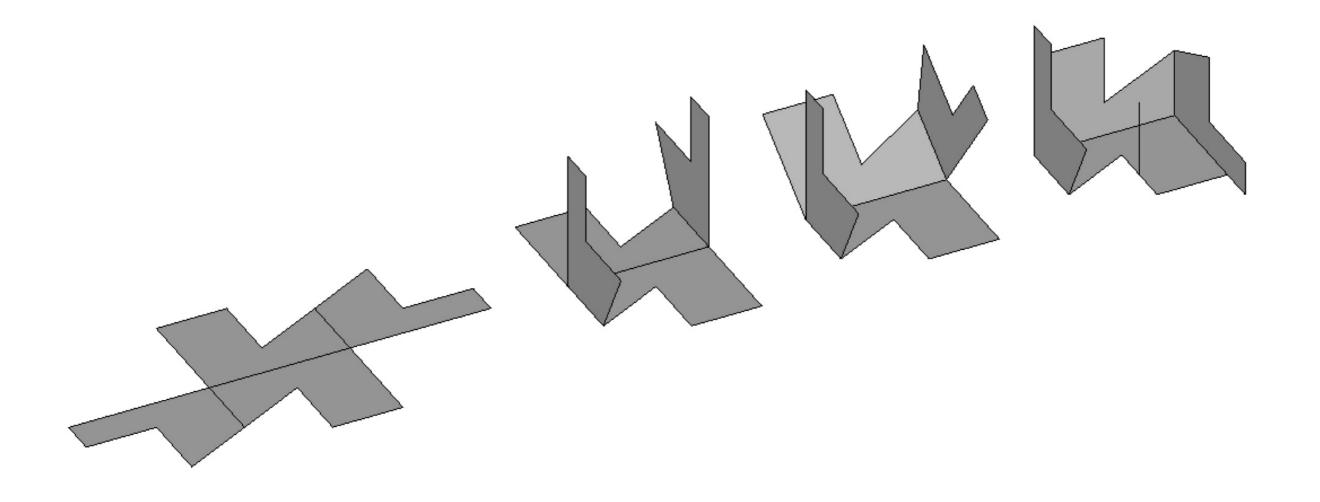


Fig. 18

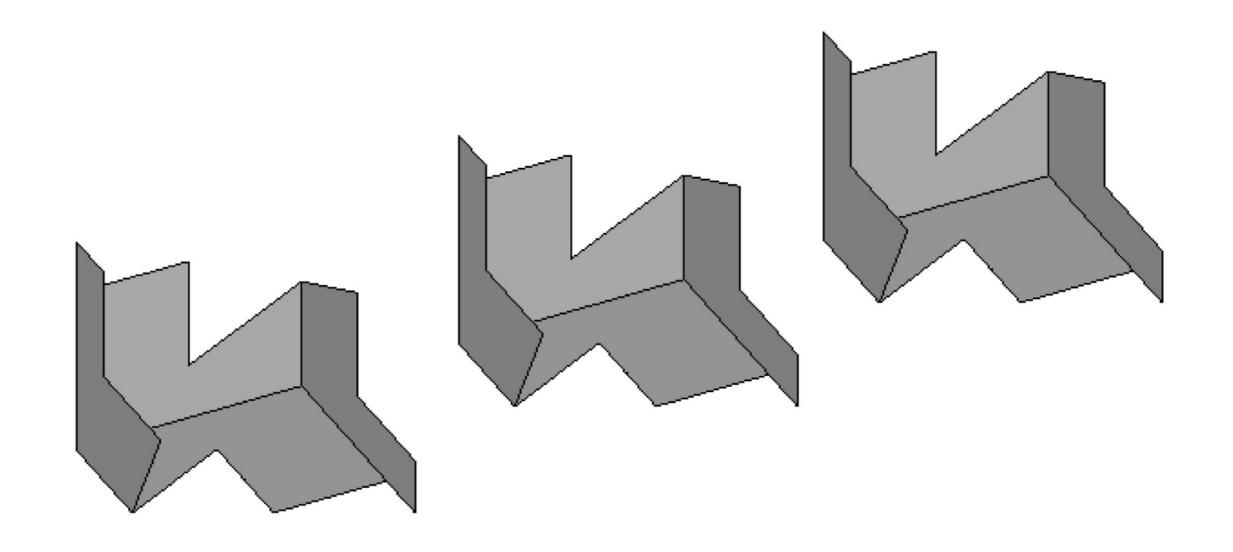


Fig. 19

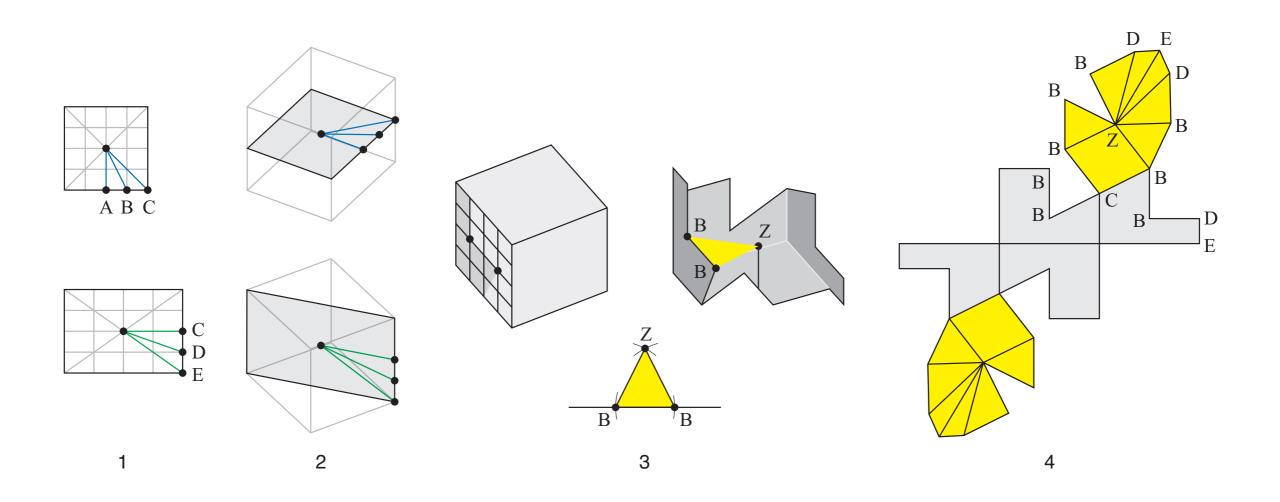


Fig. 20

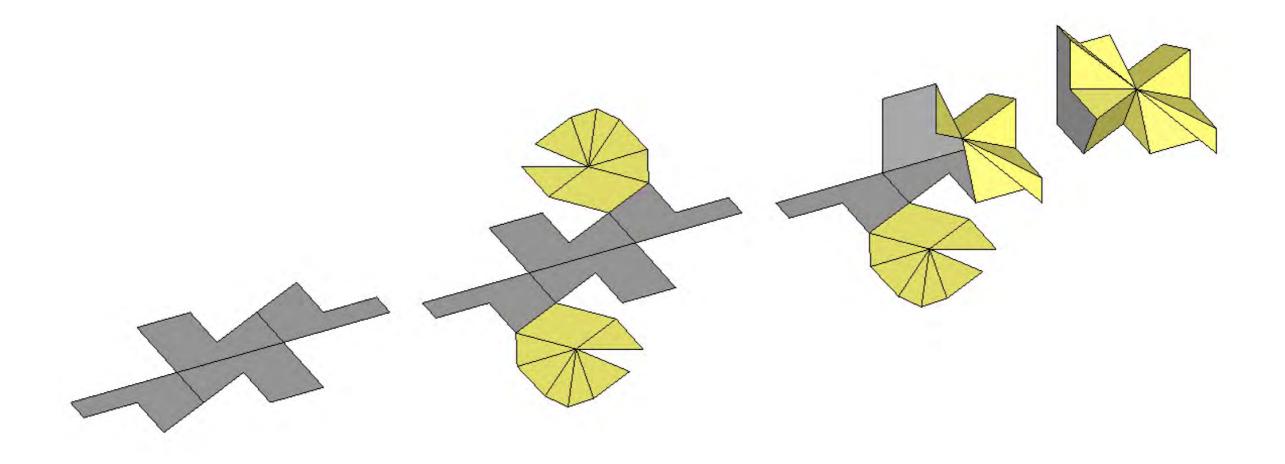


Fig. 21

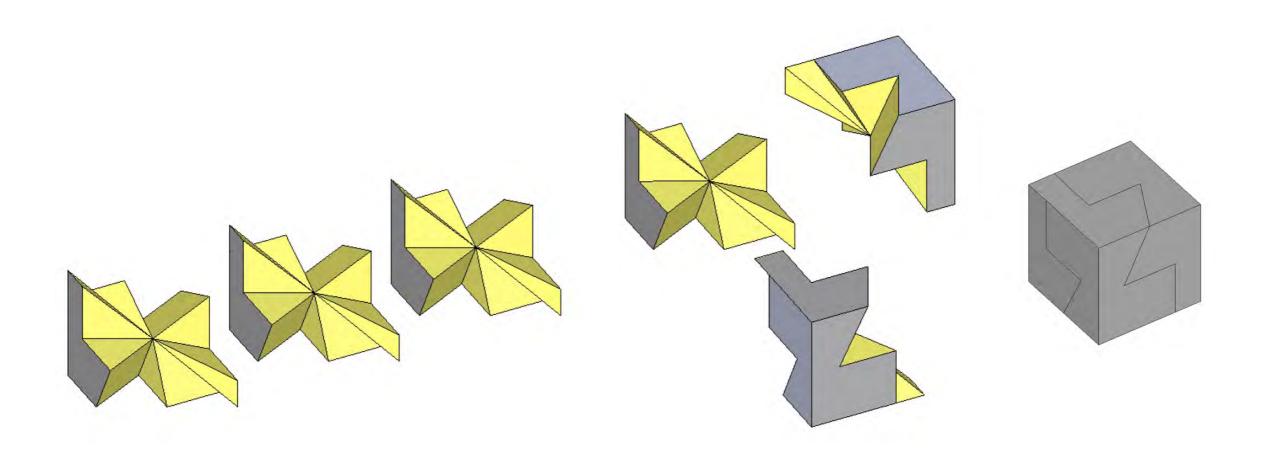
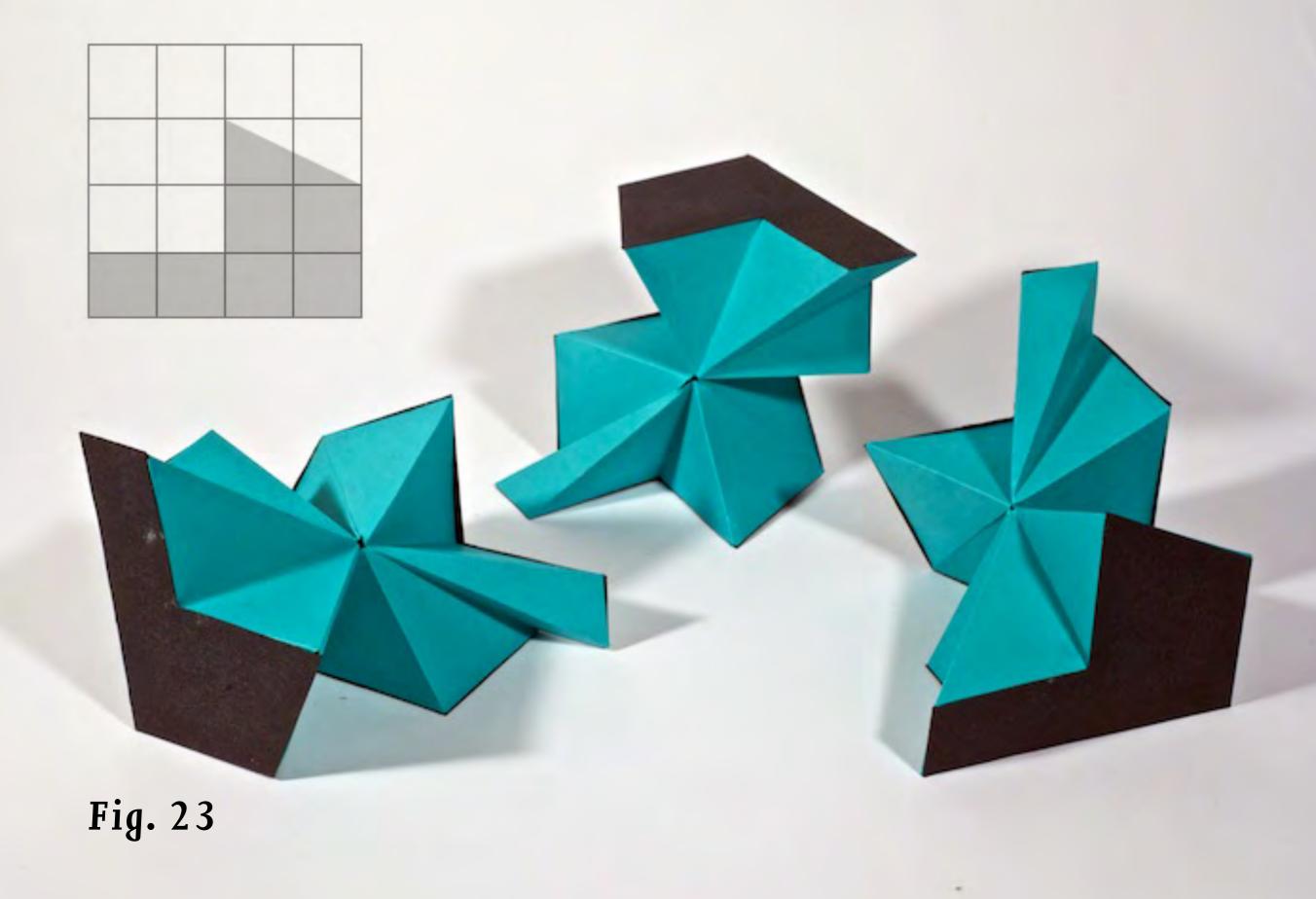


Fig. 22



HINGES AND ROTATIONS

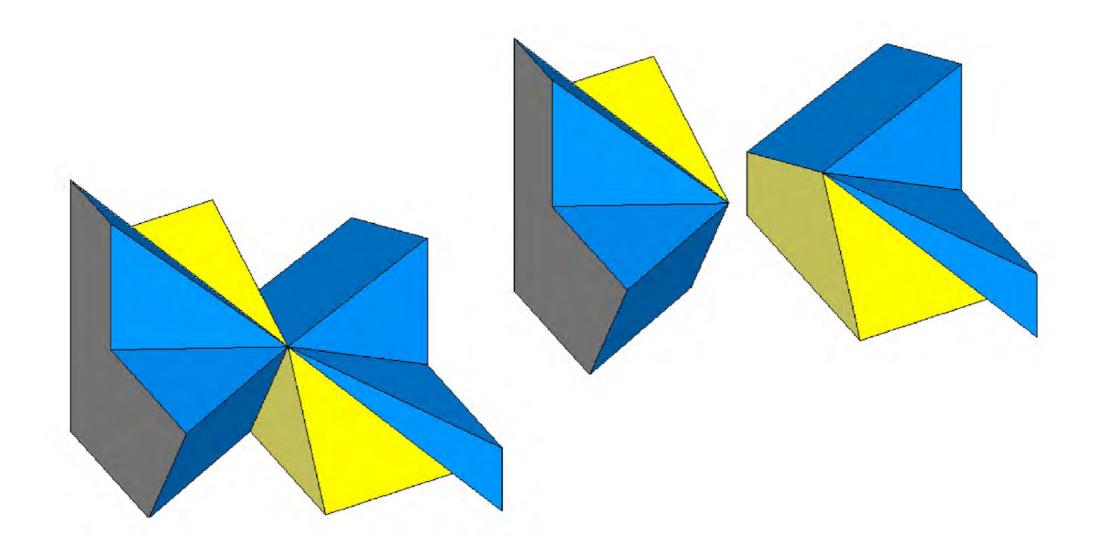


Fig. 24

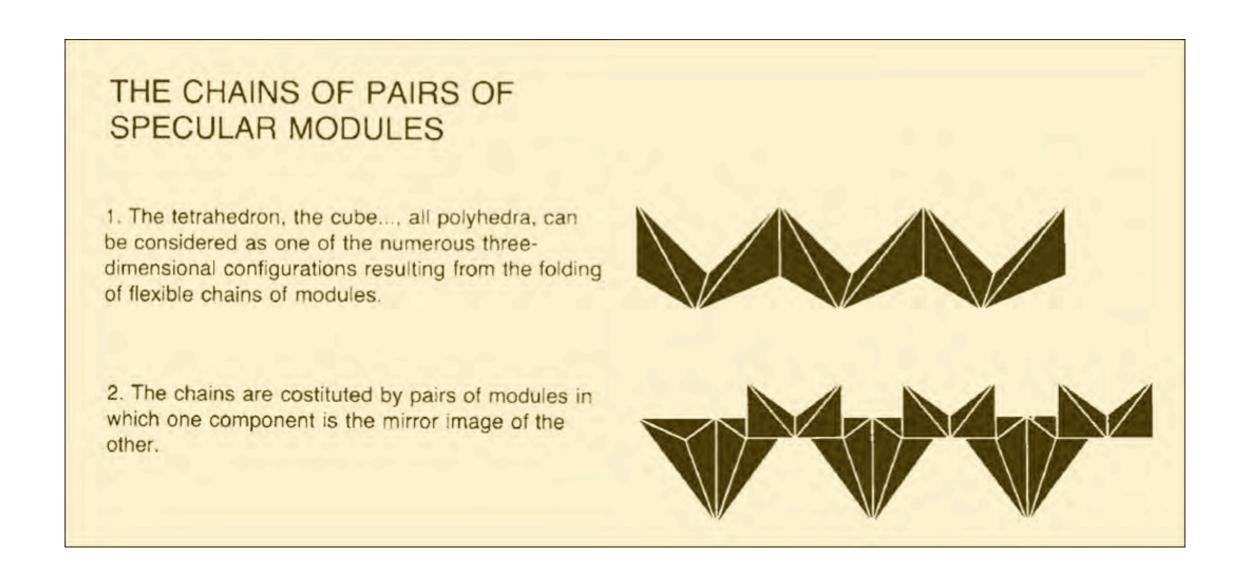


Fig. 25

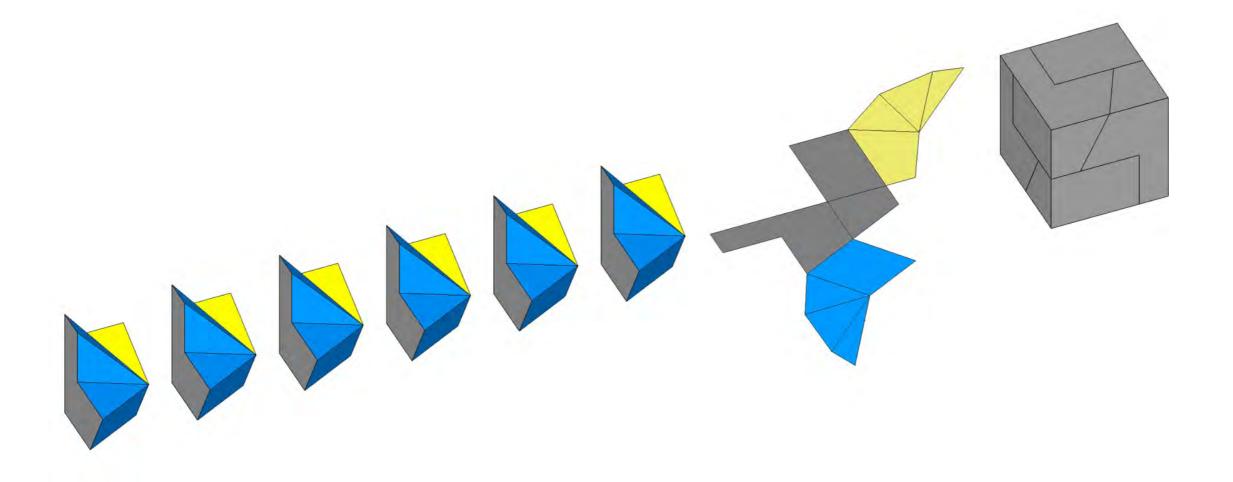


Fig. 26

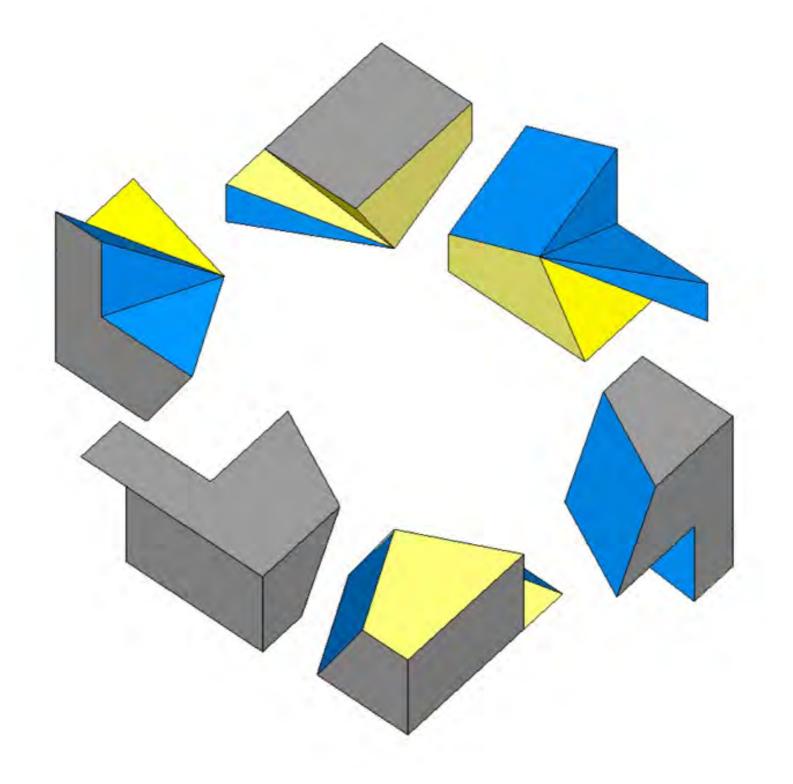


Fig. 27

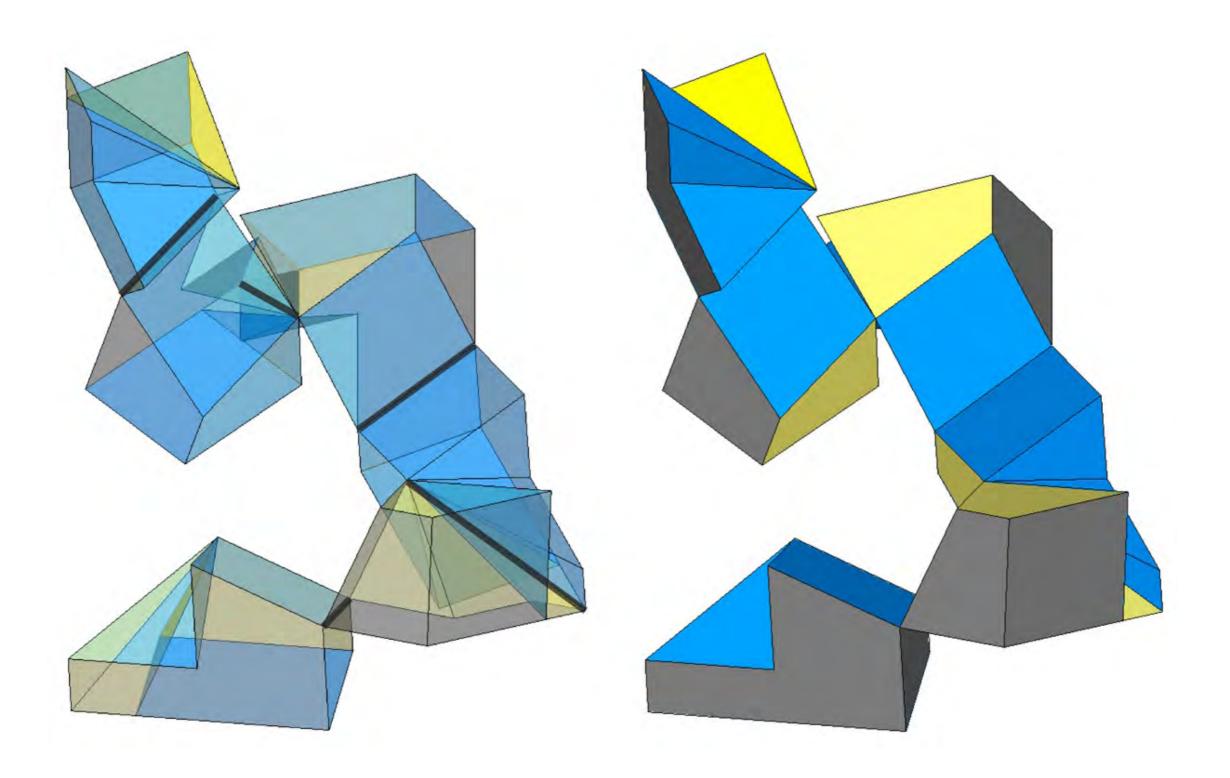
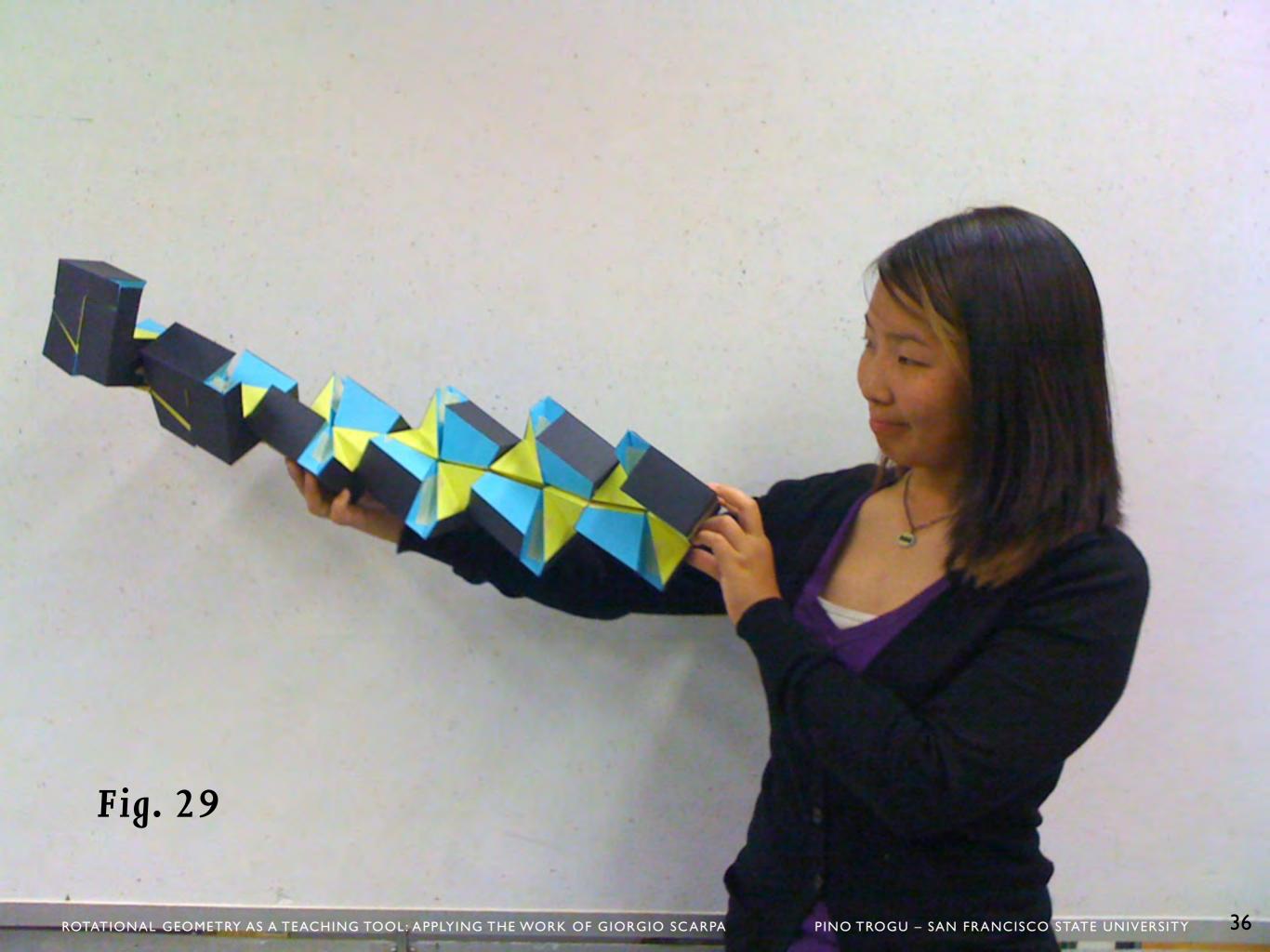
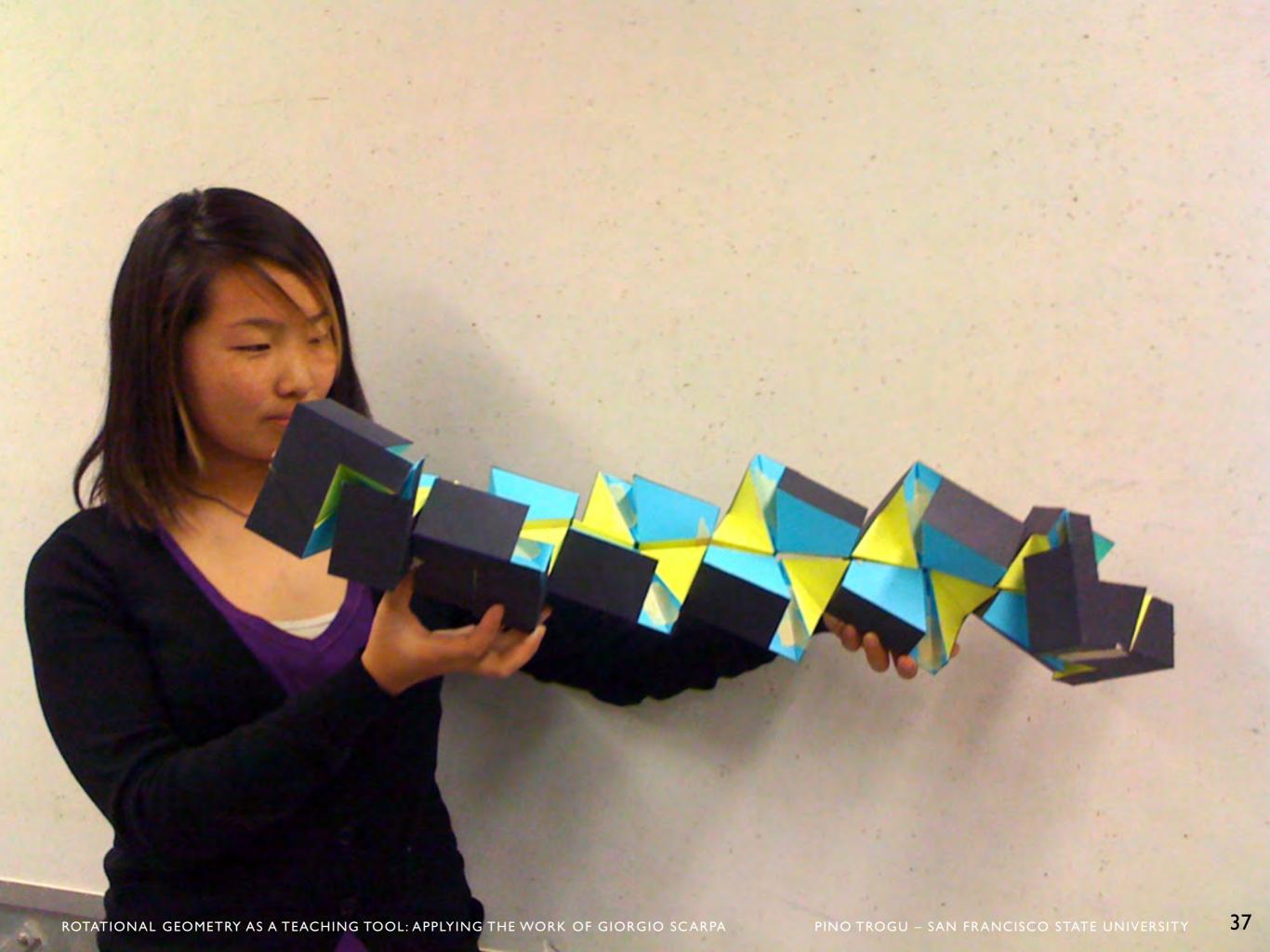
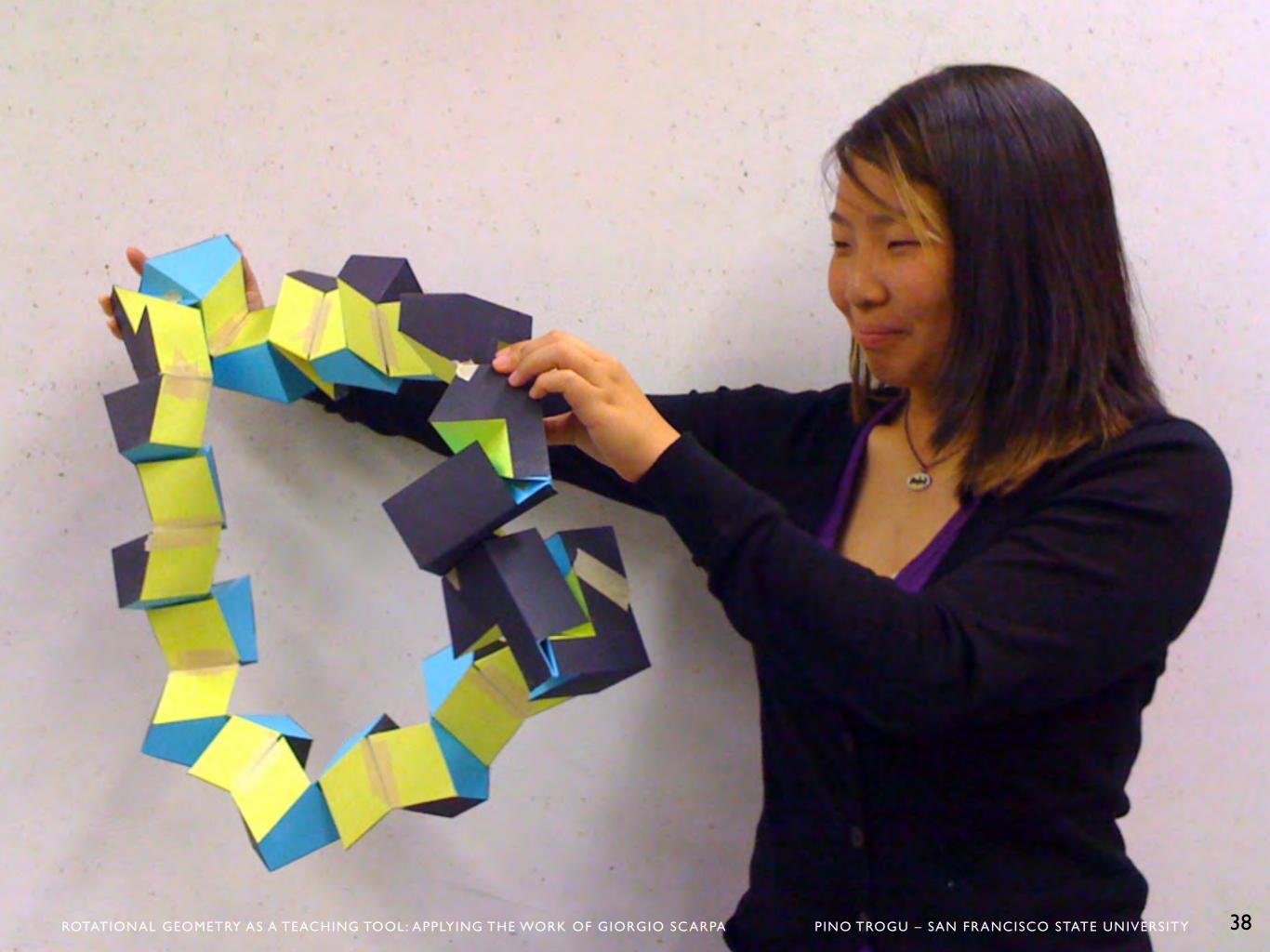
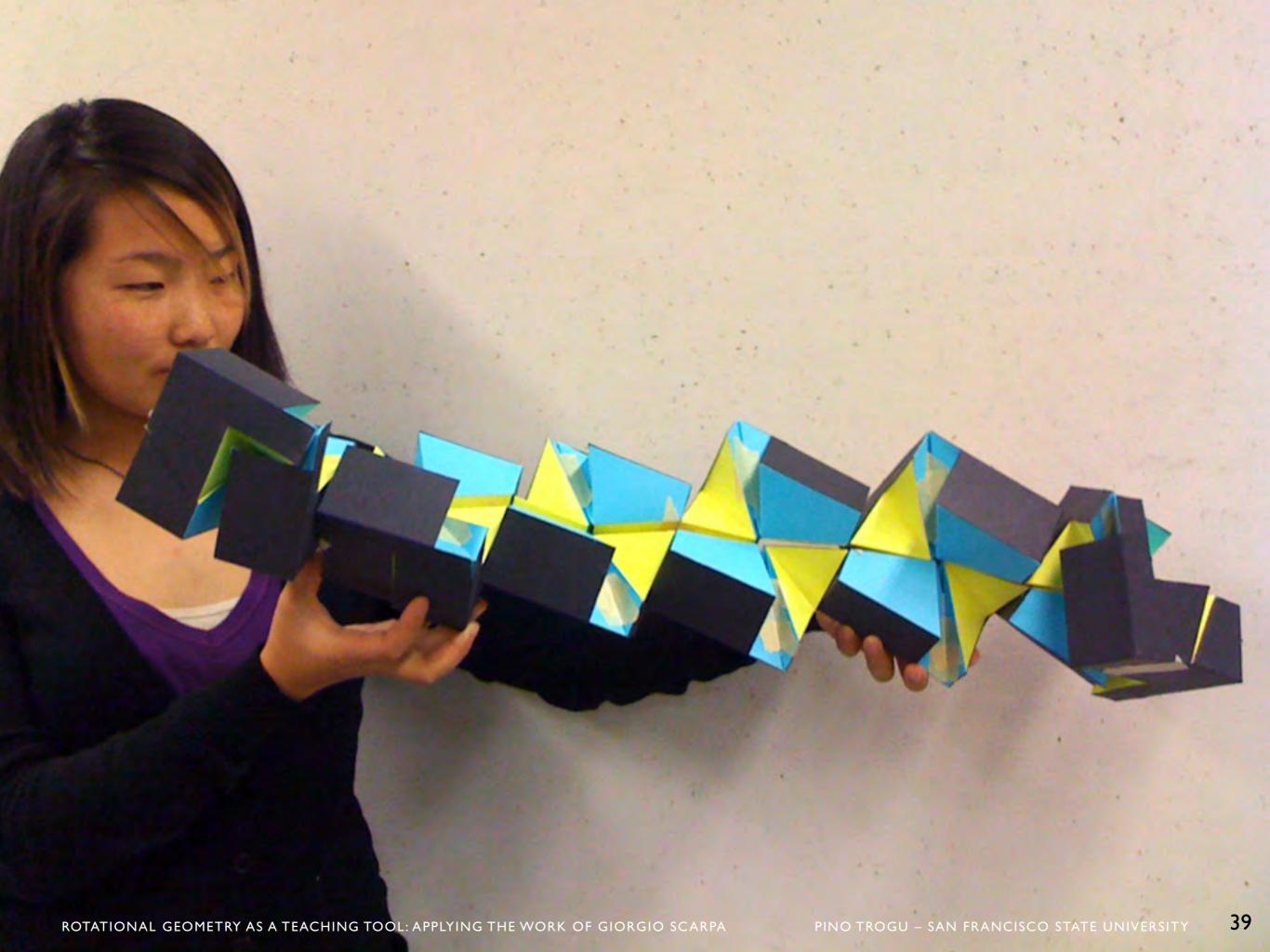


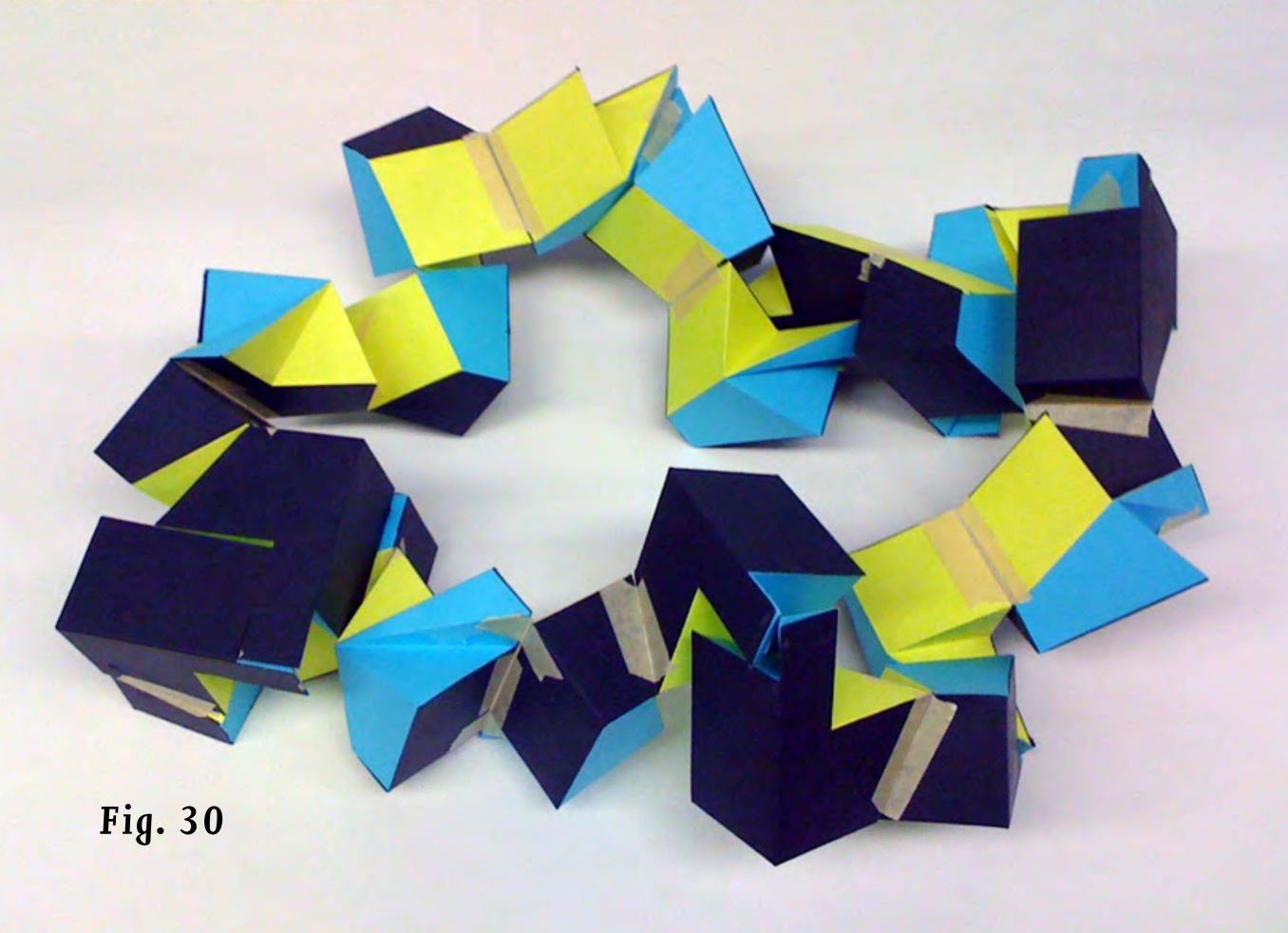
Fig. 28

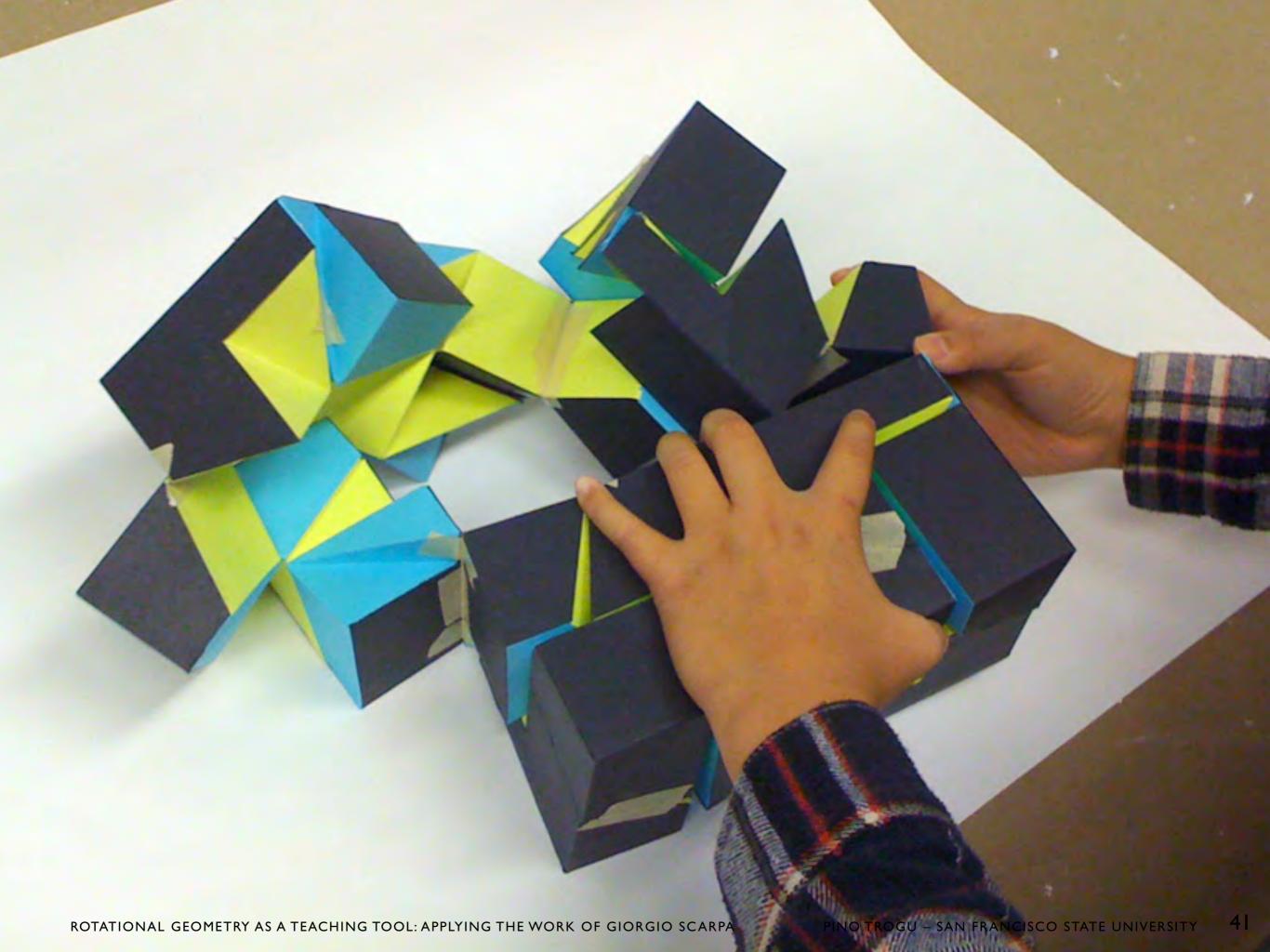


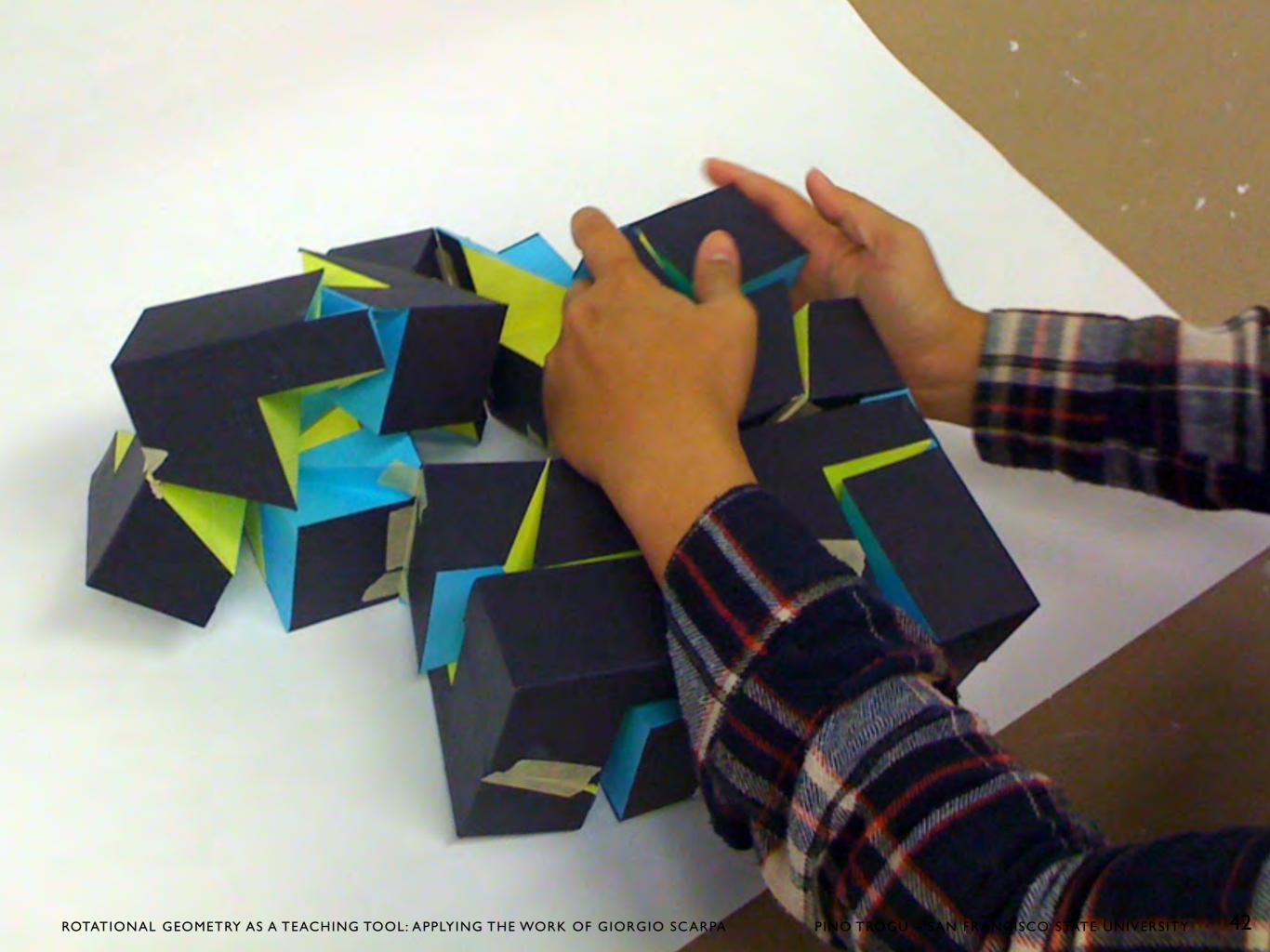


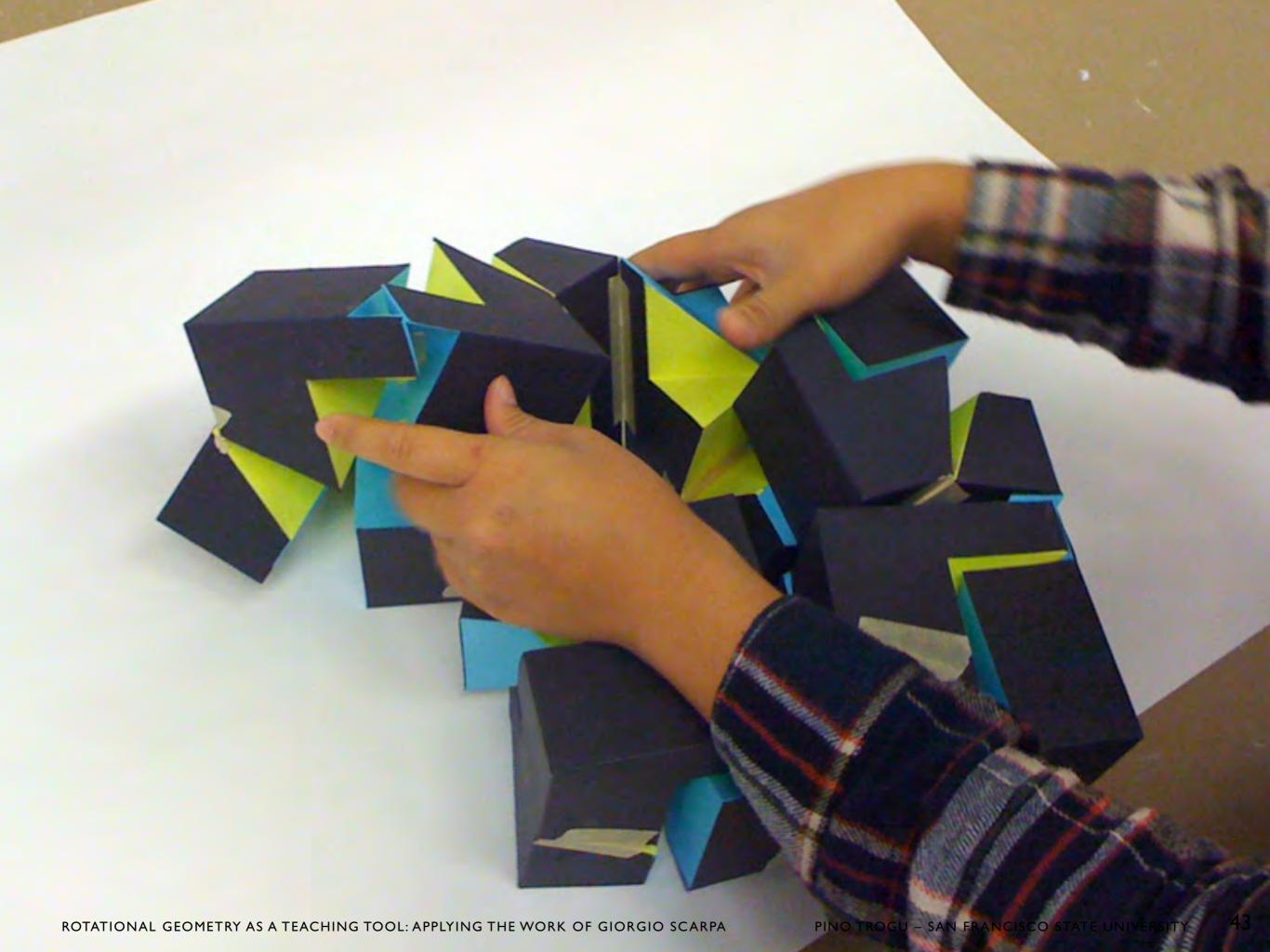


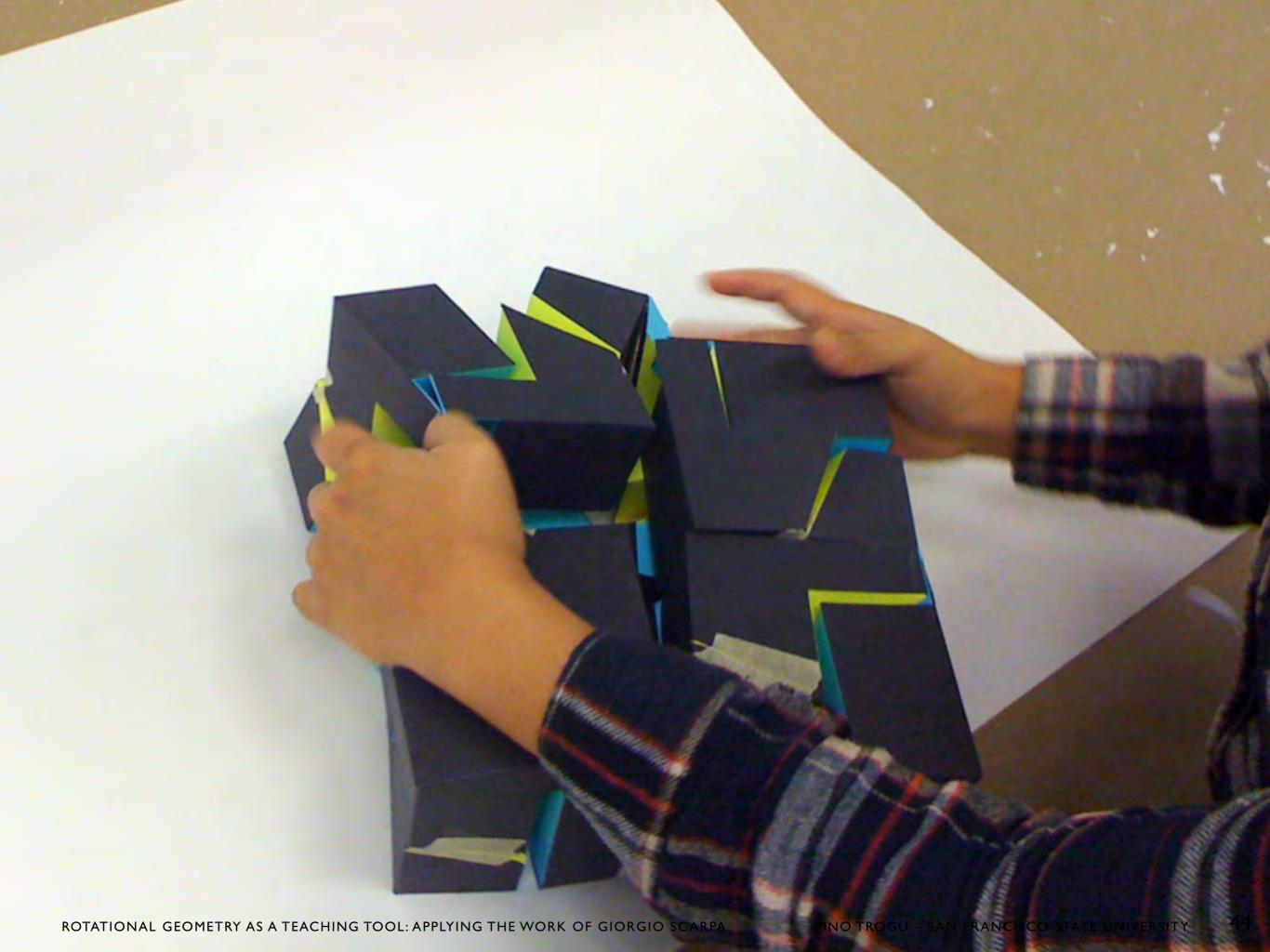






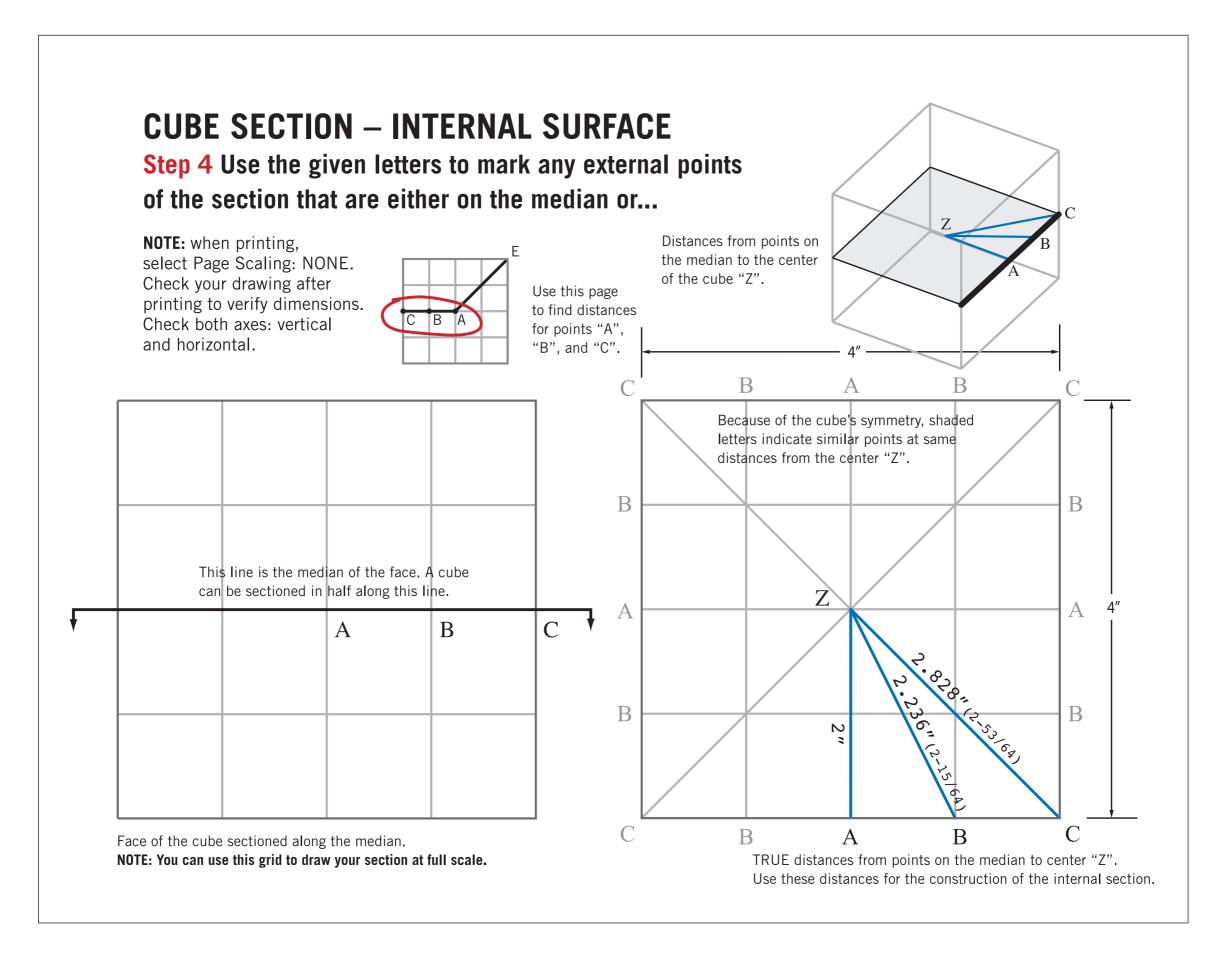






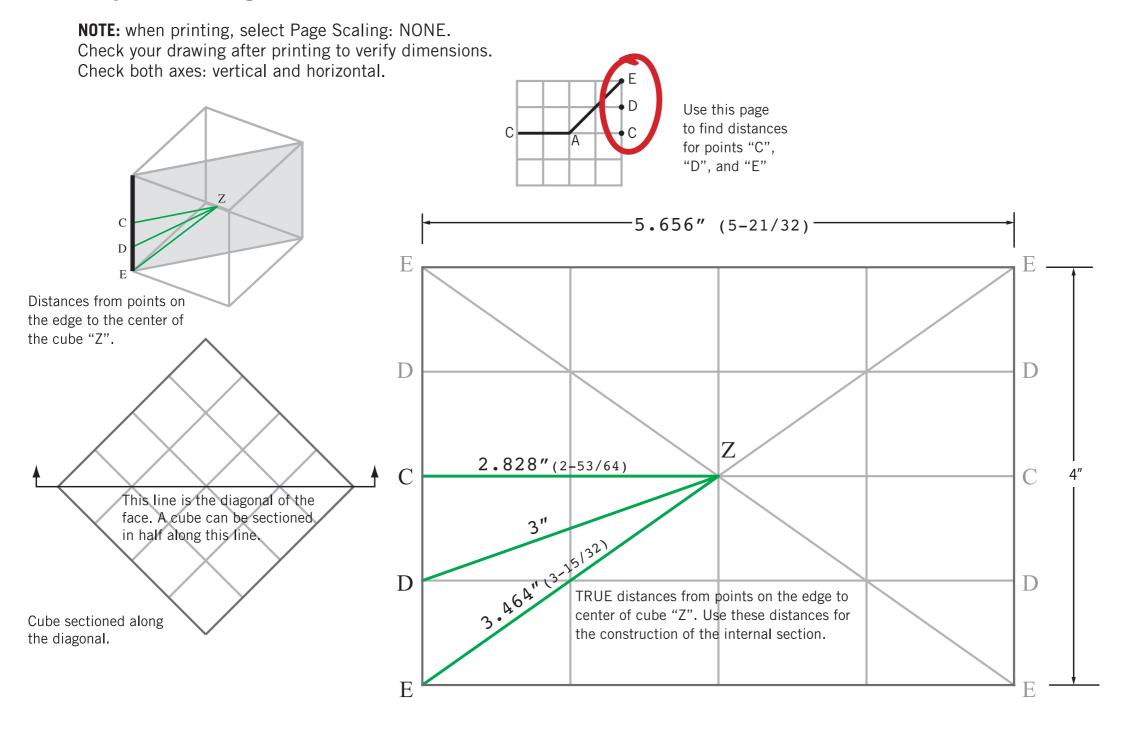






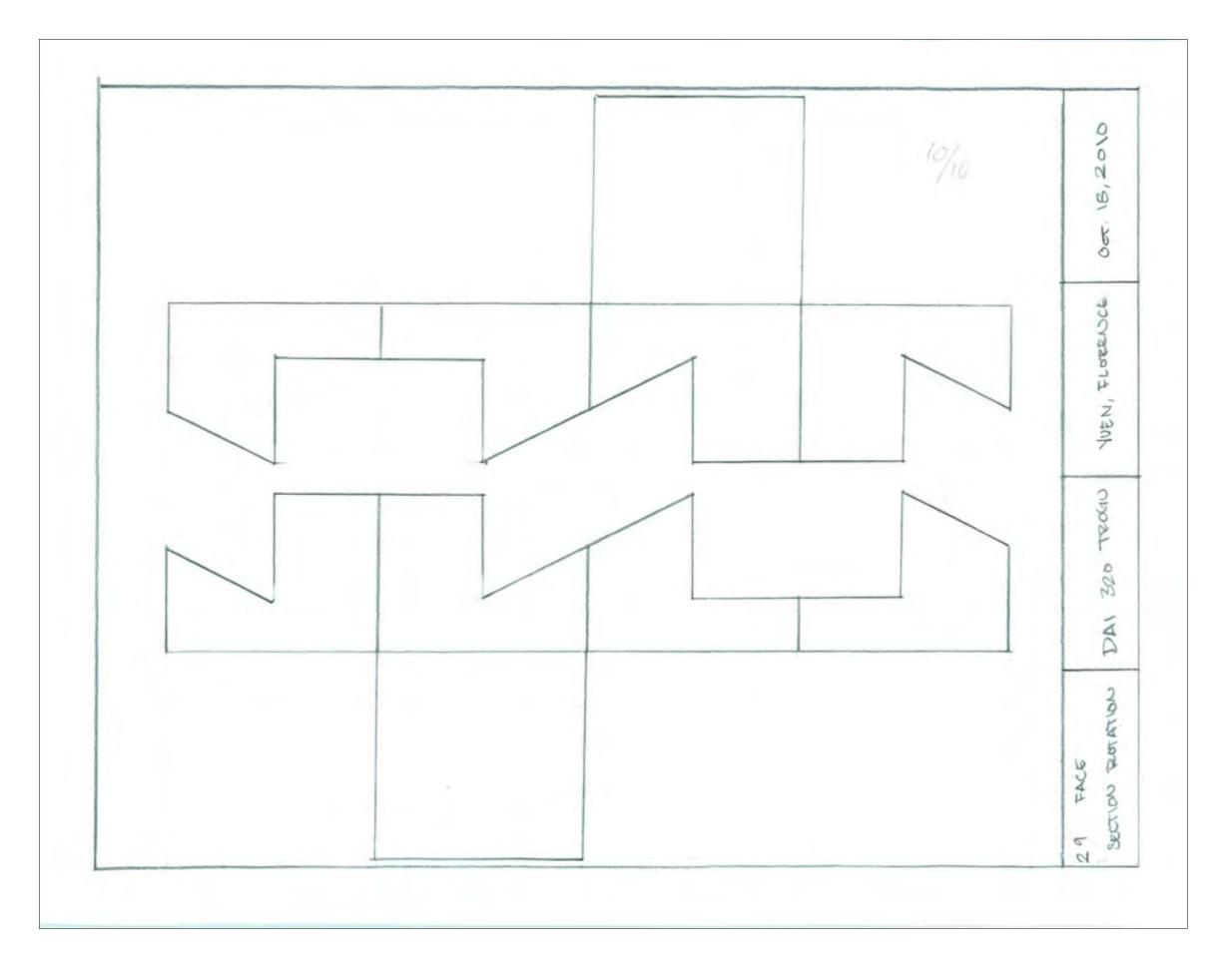
CUBE SECTION – INTERNAL SURFACE

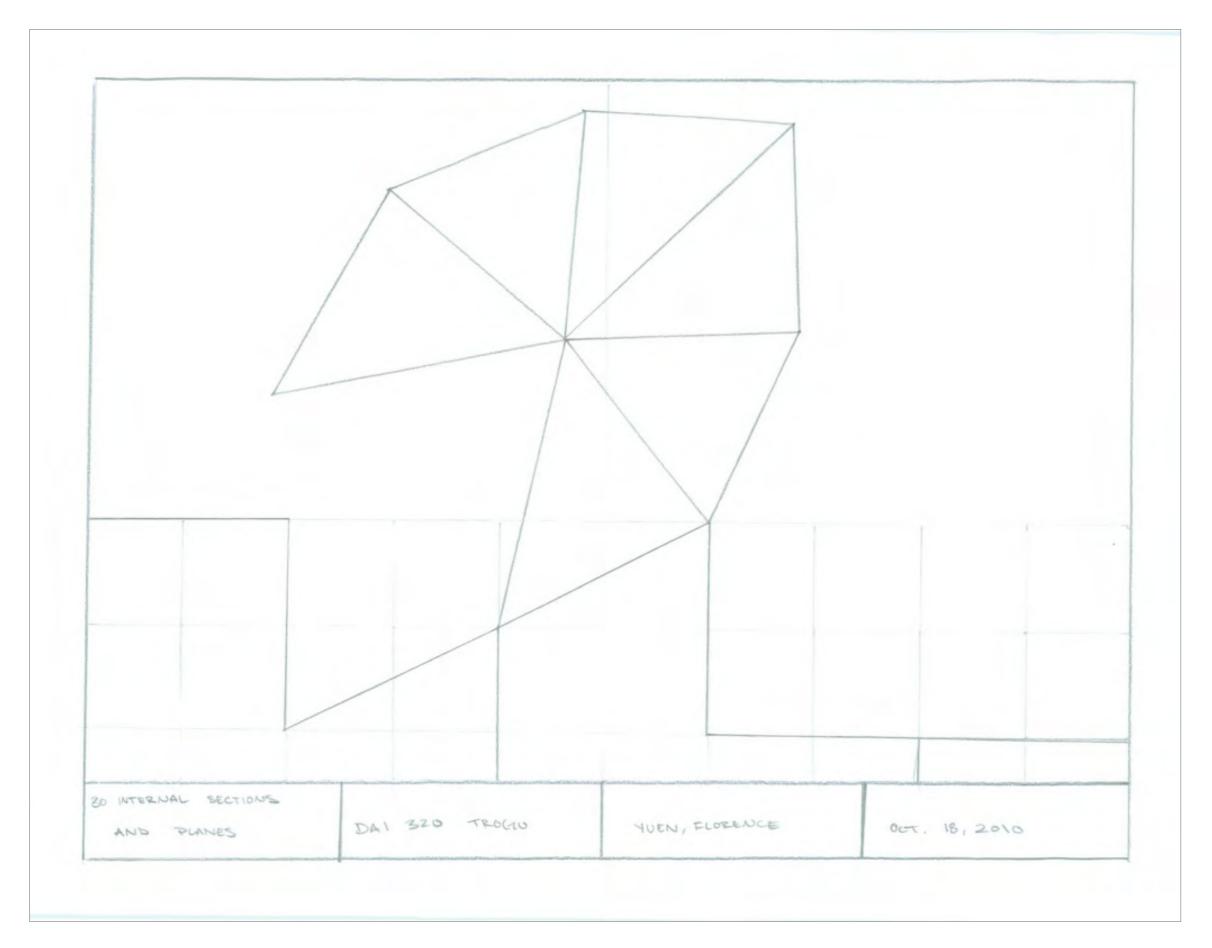
Step 4 ...the edge of the face/cube.

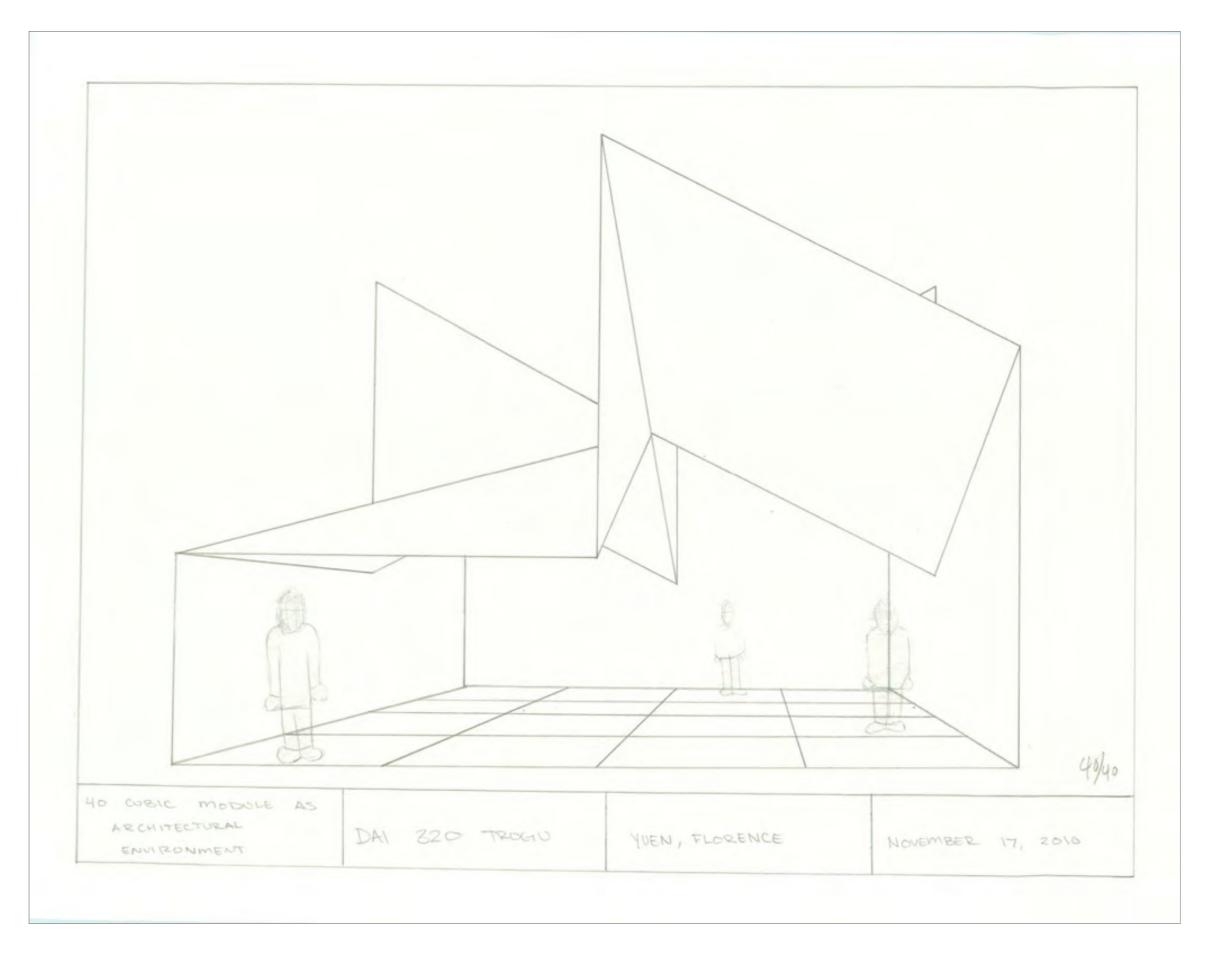


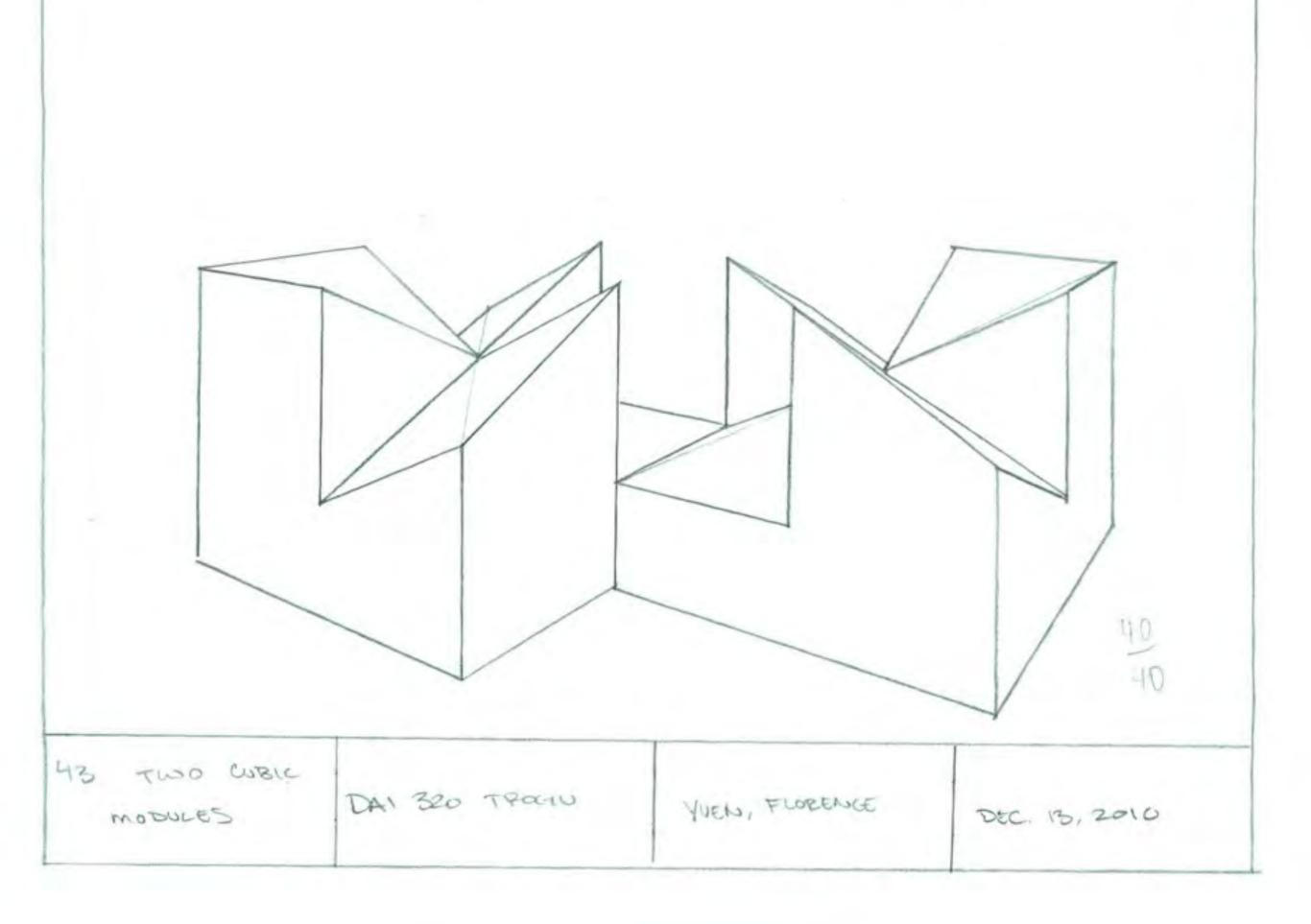


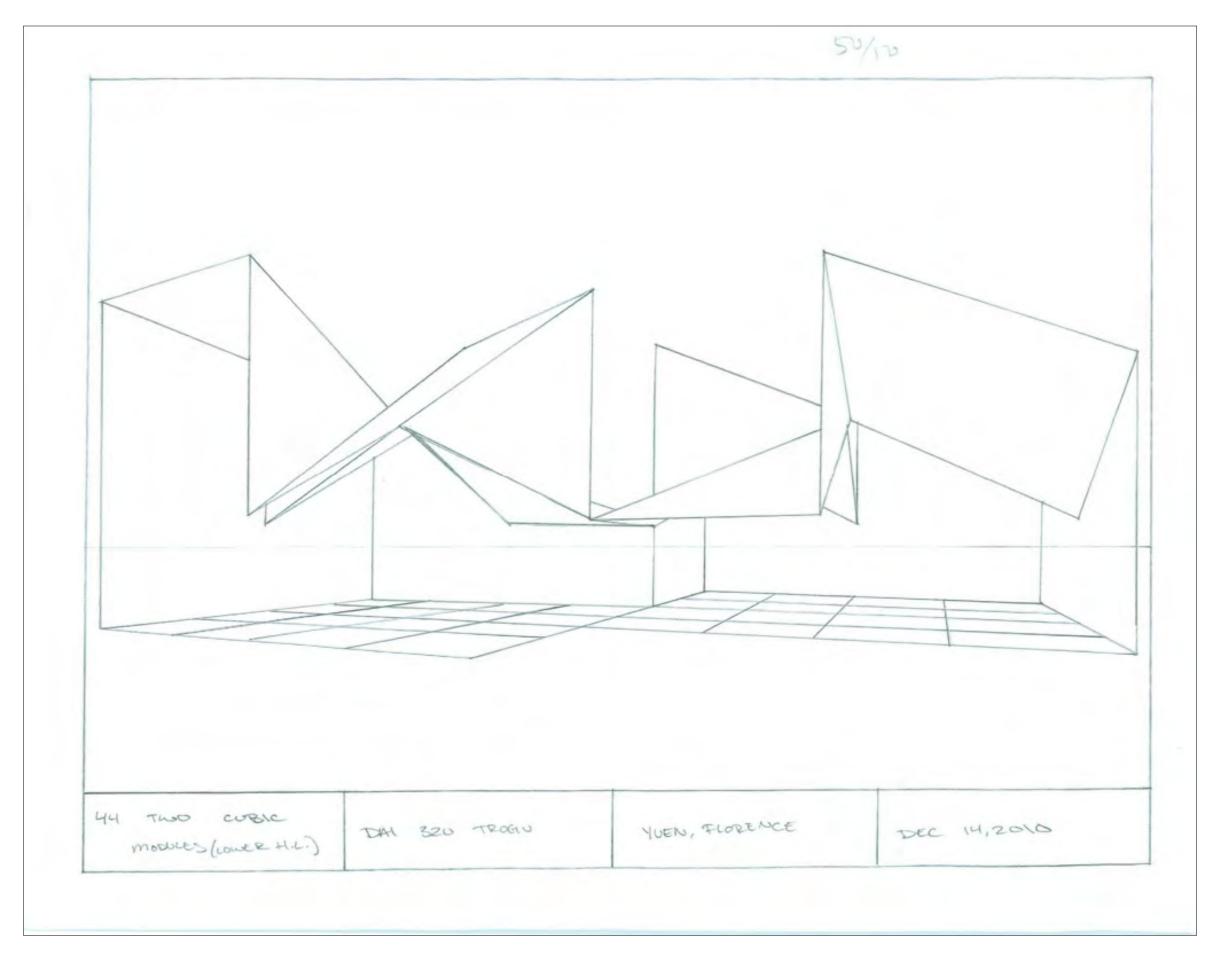


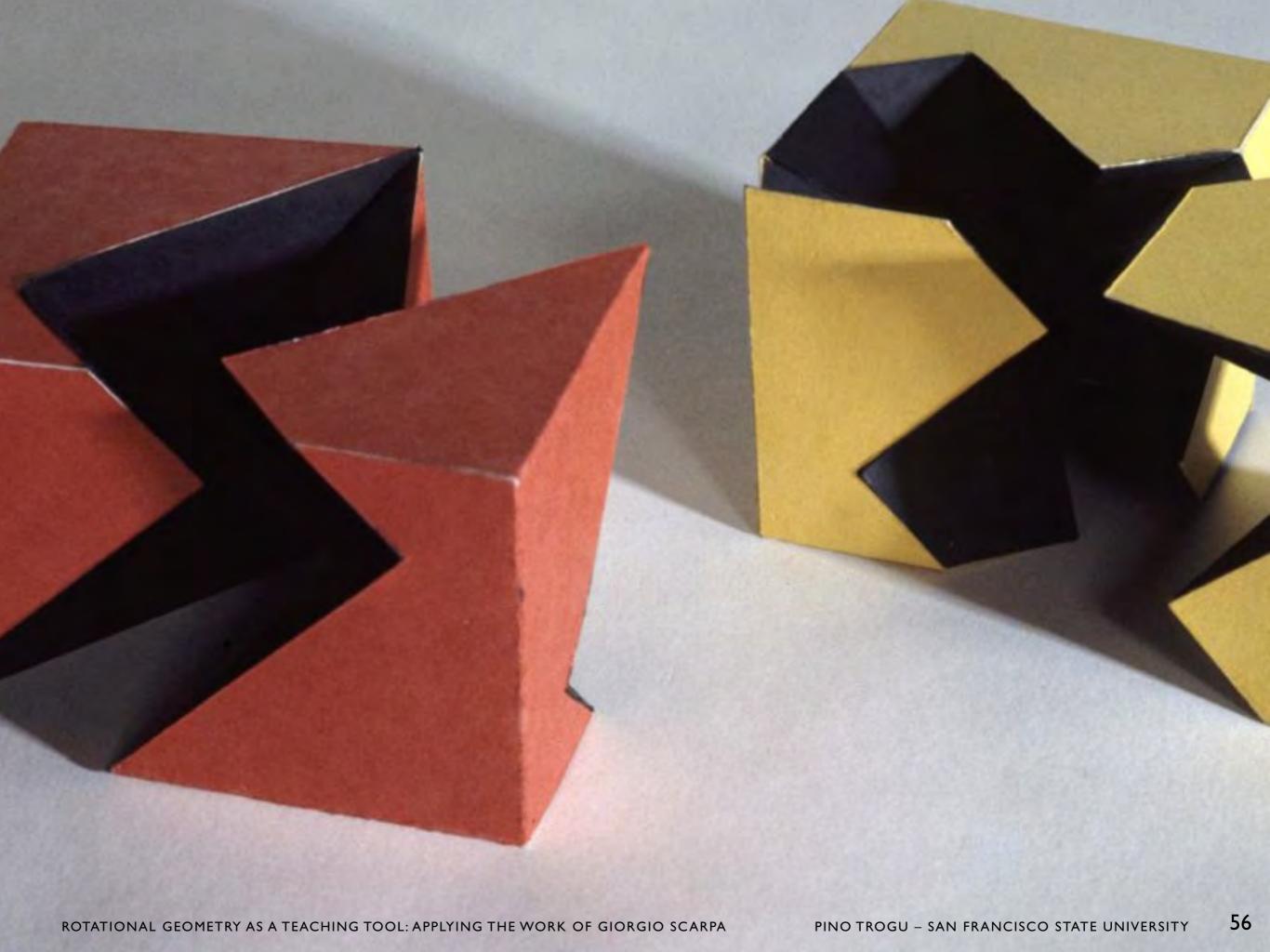


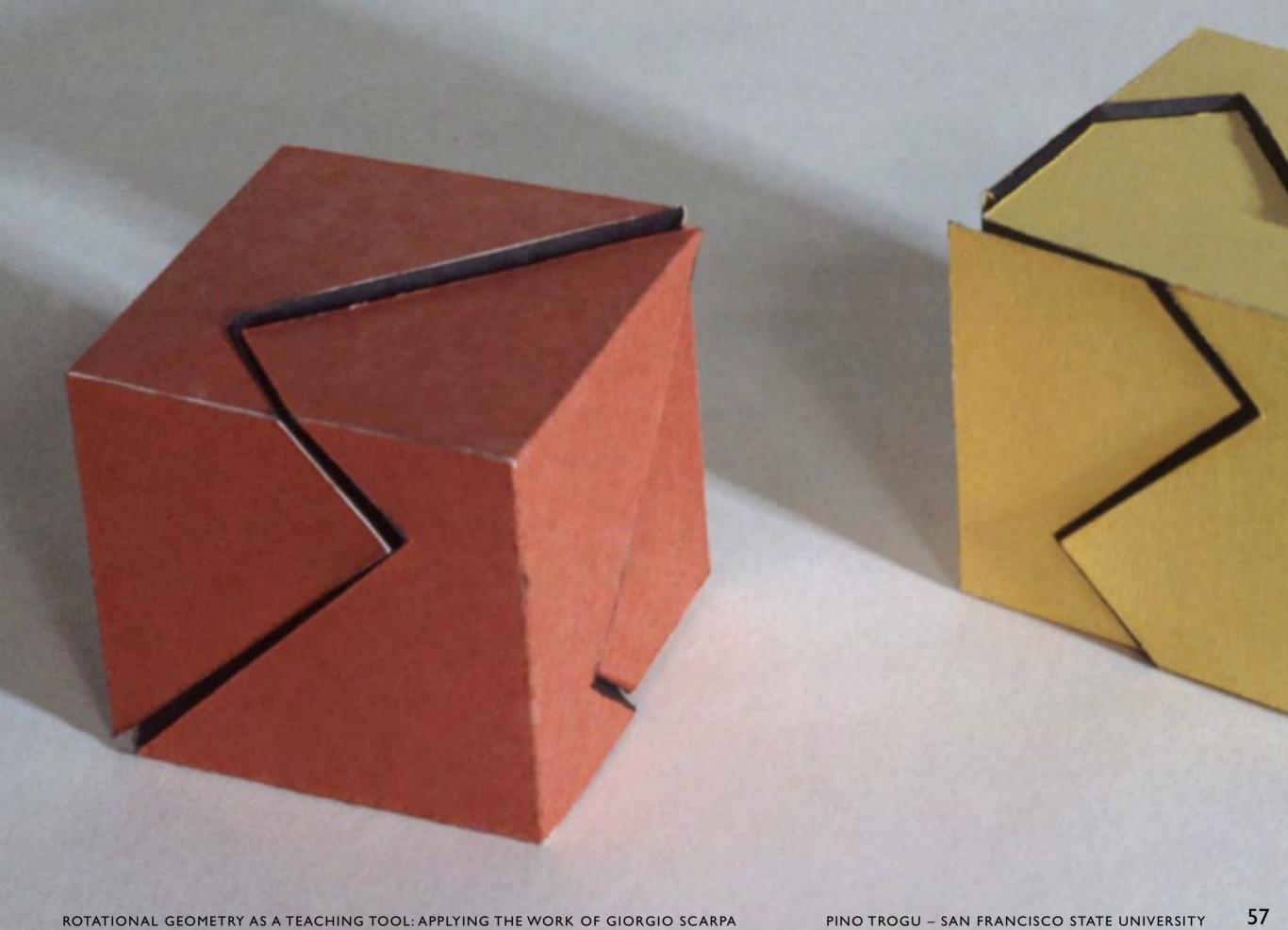


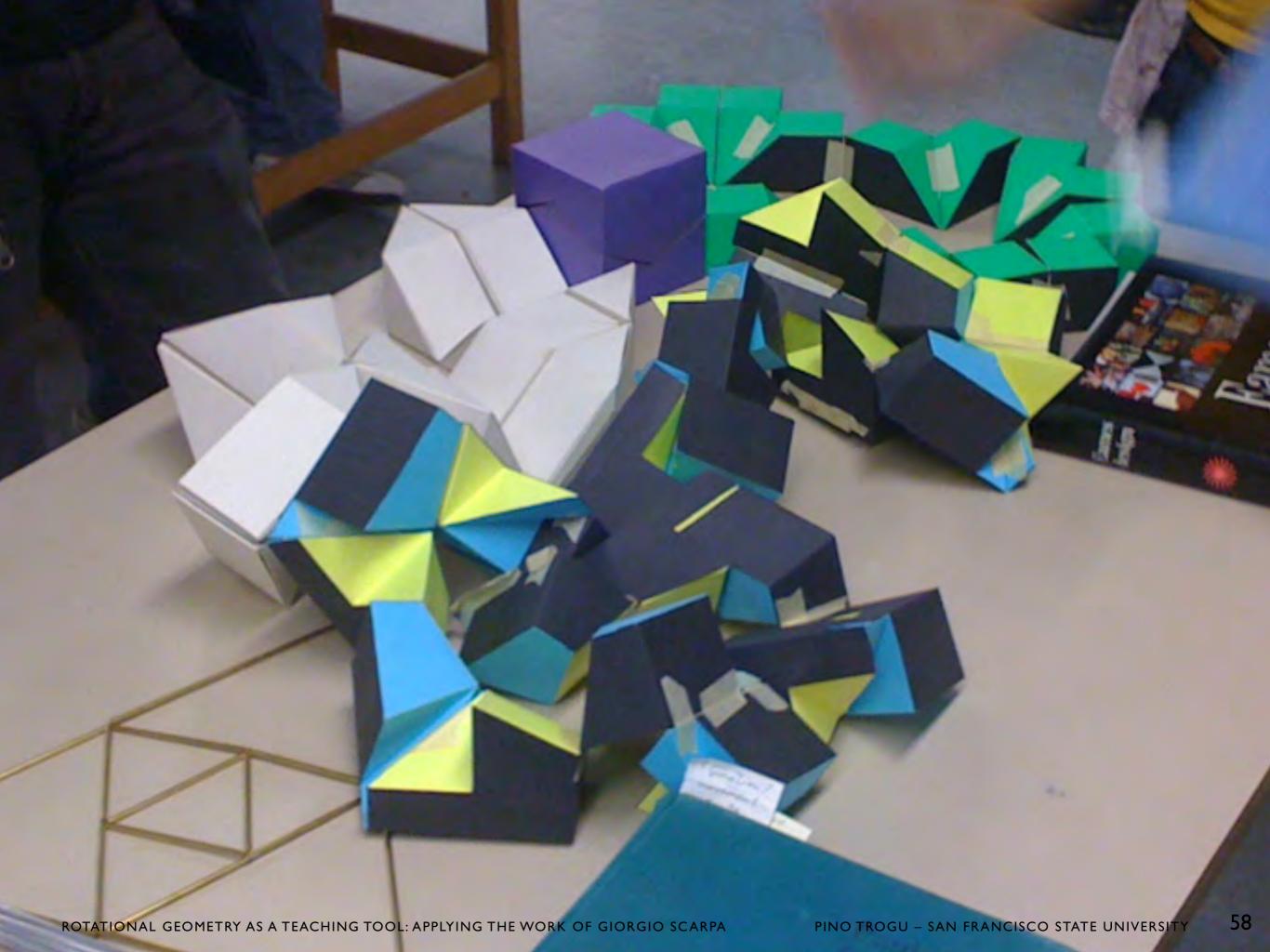


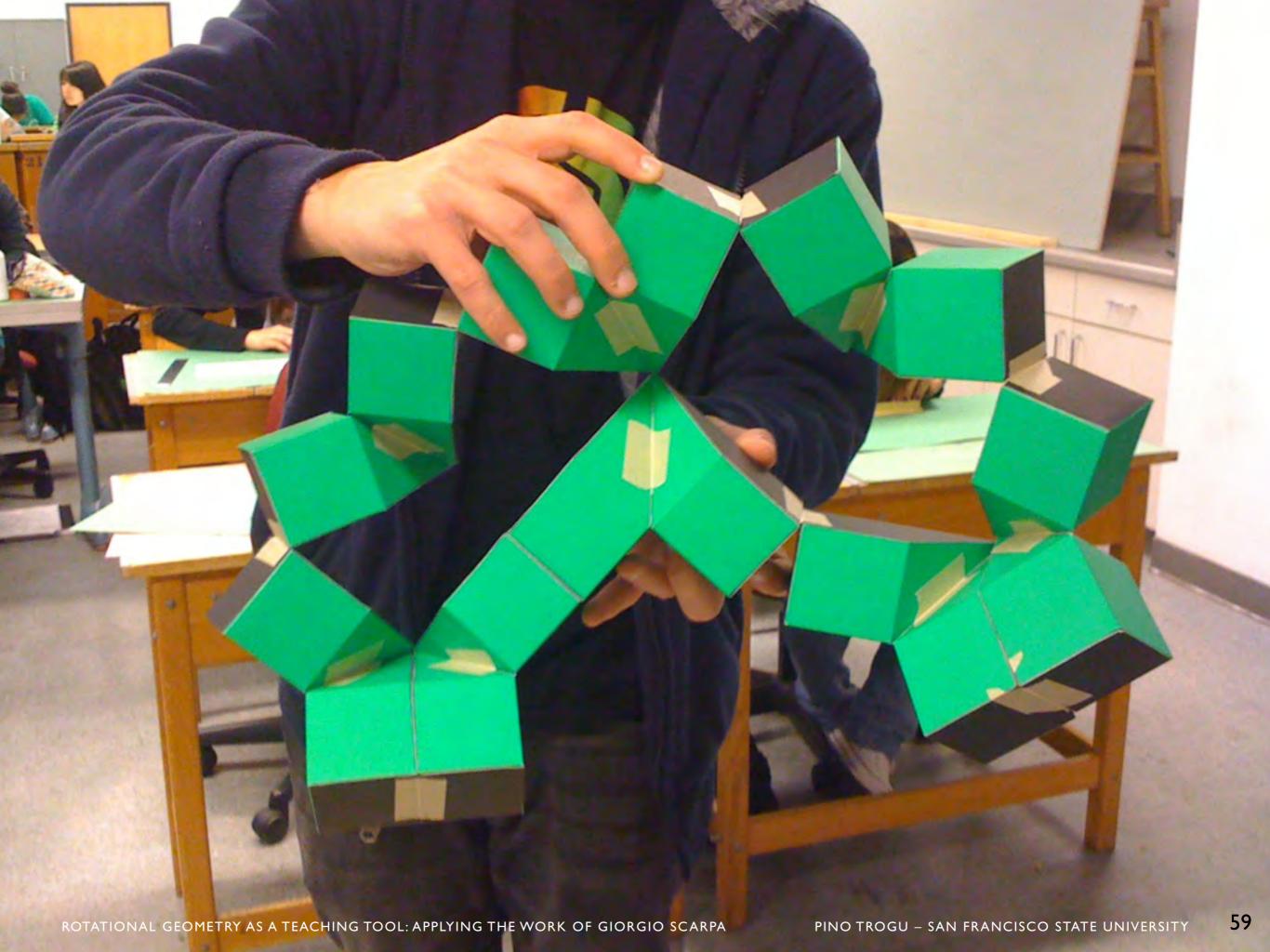












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Cube Section trogu.com/projects/getProject/20051225082001/project_html Giorgio Scarpa userwww.sfsu.edu/~trogu/scarpa

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